



## Exercise Sheet 11.

Due: Monday, 08.12.2025, 12:00.

**Exercise 1** (Optimization methods under affine transformation). Let  $F : \mathbb{R}^n \rightarrow \mathbb{R}$  be twice continuously differentiable. Furthermore, consider a  $\mathbf{x} \in \mathbb{R}^n$ , such that  $\nabla^2 F(\mathbf{x})$  is positive definite. Let  $\mathbf{M} \in \mathbb{R}^{n \times n}$  be an invertible matrix and  $\mathbf{v} \in \mathbb{R}^n$  an arbitrary vector. The new iterate  $\mathbf{x}^+ = \mathbf{x} + \mathbf{d}$  is calculated as follows:

- i. Transform to a new “y” coordinate system:  $\mathbf{x} = \mathbf{x}(\mathbf{y}) := \mathbf{M}\mathbf{y} + \mathbf{v}$ .
  - ii. Take a gradient step in the “y” coordinate system:  $\mathbf{y}^+ = \mathbf{y} - \nabla_{\mathbf{y}} F(\mathbf{x}(\mathbf{y}))$ .
  - iii. Transform back to the “x” coordinate system:  $\mathbf{x}^+ = \mathbf{x}(\mathbf{y}^+)$ .
- (a) Give a formula for  $\mathbf{d}$  which depends only on  $\mathbf{M}$  and  $\nabla F(\mathbf{x})$ .
- (b) How  $\mathbf{M}$  should be chosen so that  $\mathbf{d}$  is a gradient step at the point  $\mathbf{x}$ ? For which  $\mathbf{M}$  does  $\mathbf{d}$  correspond to a Newton step at the point  $\mathbf{x}$ ?

**Exercise 2** (Optimization of a quadratic function). We consider the iteration

$$x_{k+1} = x_k + \alpha_k p_k$$

with  $x_0 = 2$  to minimize  $f(x) = x^2$  and want to investigate the behavior of the sequence  $\{x_k\}$  for  $k \rightarrow \infty$ .

- (a) Show that for  $p_k = (-1)^{k+1}$  and  $\alpha_k = 2 + 3/2^{k+1}$ ,  $x_k = (-1)^k + (-1/2)^k$  holds.
- (b) Show that for  $p_k = -1$  and  $\alpha_k = 1/2^{k+1}$ ,  $x_k = 1 + 1/2^k$  holds.

**Exercise 3** (Sherman-Morrison-Woodbury formula). Let  $\mathbf{A} \in \mathbb{R}^{n \times n}$  be an invertible matrix and  $\mathbf{u}, \mathbf{v} \in \mathbb{R}^n$  arbitrary vectors. Show that:

- (a) If  $\mathbf{v}^T \mathbf{A}^{-1} \mathbf{u} = -1$ , then  $(\mathbf{A} + \mathbf{u}\mathbf{v}^T)$  is singular.
- (b) If  $\mathbf{v}^T \mathbf{A}^{-1} \mathbf{u} \neq -1$ , then

$$(\mathbf{A} + \mathbf{u}\mathbf{v}^T)^{-1} = \mathbf{A}^{-1} - \frac{1}{1 + \mathbf{v}^T \mathbf{A}^{-1} \mathbf{u}} \mathbf{A}^{-1} \mathbf{u} \mathbf{v}^T \mathbf{A}^{-1}.$$