

# Chapter 4

## Phylogenetic Trees

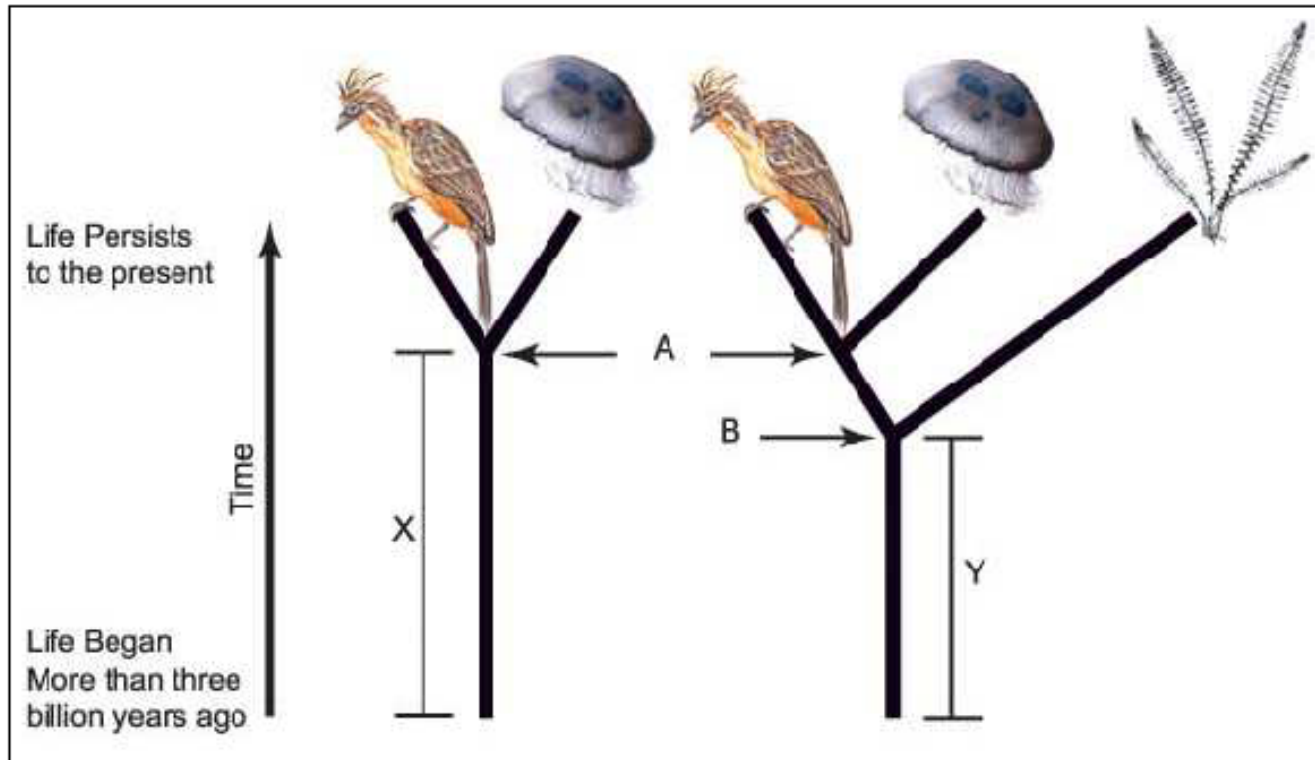


Figure 8.1 in R. Shamir, Orly Stettiner, R. Gabor: Algorithms for Molecular Biology 8.1 Preface: Phylogenetics and Phylogenetic Trees

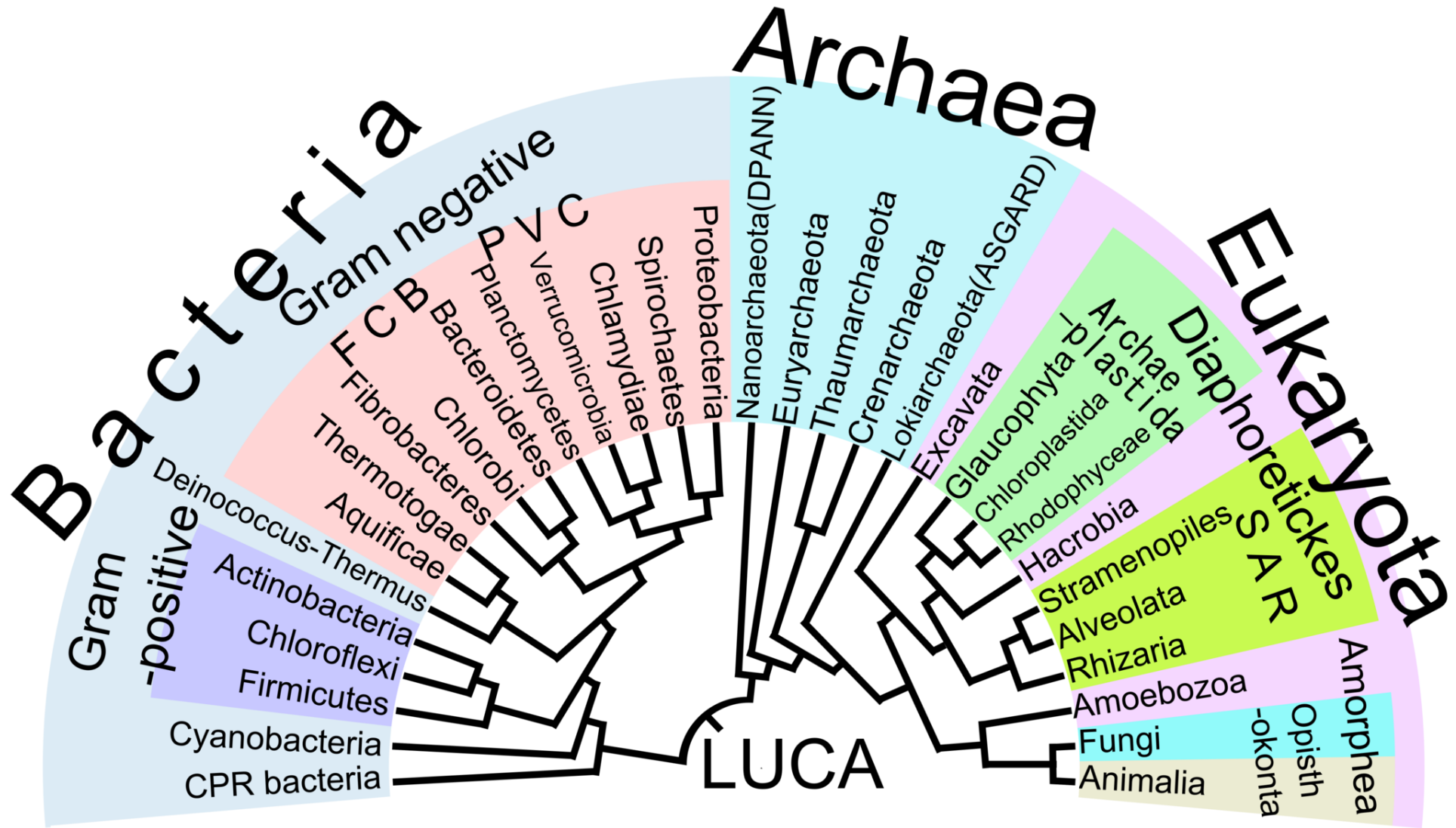
- A: most recent common ancestor of bird and jellyfish
- X: portion of history shared by bird and jellyfish

# What is Phylogenetics?

- Find the **evolutionary relationships** between species.
- **Basic idea**: compare specific features of the species.  
**Assumption**: similar species are genetically close.
- The term **phylogeny** refers to these relationships, usually presented as a **phylogenetic tree**.
- Classic phylogeny: **physical or morphological features** – size, color, shape, number of legs, ...
- **Modern phylogeny** uses information extracted from genetic material – mainly **DNA and protein sequences**.

Features (characters): DNA or protein sites within **conserved blocks of multiple alignments**.

# The Tree of Life



**LUCA: Last universal common ancestor: the most recent common ancestor of all current life on Earth.**

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[https://commons.wikimedia.org/wiki/File:Phylogenetic\\_Tree\\_of\\_Life.png](https://commons.wikimedia.org/wiki/File:Phylogenetic_Tree_of_Life.png)

# Approaches To Phylogenetic Tree Construction

## Distance based methods:

require definition of a **distance function between objects**.

Construct tree so that the pairwise distances can be mapped to the tree **as accurately as possible**.

## Character based methods:

**character** or **trait** = a discrete property of an object. E.g.

- “mammal” (all animals are either mammals or not)
- “unicellular” (either unicellular or multicellular)

Species are grouped according to similarity of characters.

## Probabilistic methods:

Classification may be based on the **likelihood** of a certain tree explaining the set of objects.

Alternative: **Bayesian approach**. Combine likelihood with prior over trees  $\rightsquigarrow$  posterior distribution of trees.

# Phylogenetic Trees

- Phylogenetic information usually represented as a **tree**:
  - every node represents a species,
  - edges represent the genetic connections.
- Difference between leaf nodes  $\rightsquigarrow$  **real species**,  
and internal nodes  $\rightsquigarrow$  **hypothetical evolutionary ancestors**.
- **Phylogenetic trees** take several forms:
  - **rooted**  $\rightsquigarrow$  one of the nodes is the root  
 $\rightsquigarrow$  **direction of ancestral relationships is determined**,
  - **unrooted**  $\rightsquigarrow$  induces no hierarchy,
  - **binary** (or bifurcating)  $\rightsquigarrow$  a node has only 0 to 2 subnodes,
  - general (not covered here).

# A Simple Solution?

**Trivial solution:** enumerate over all possible trees and calculate the target function for each one.

**Problem:** number of non-isomorphic, labeled, binary, rooted trees containing  $n$  leaves, is super-exponential:

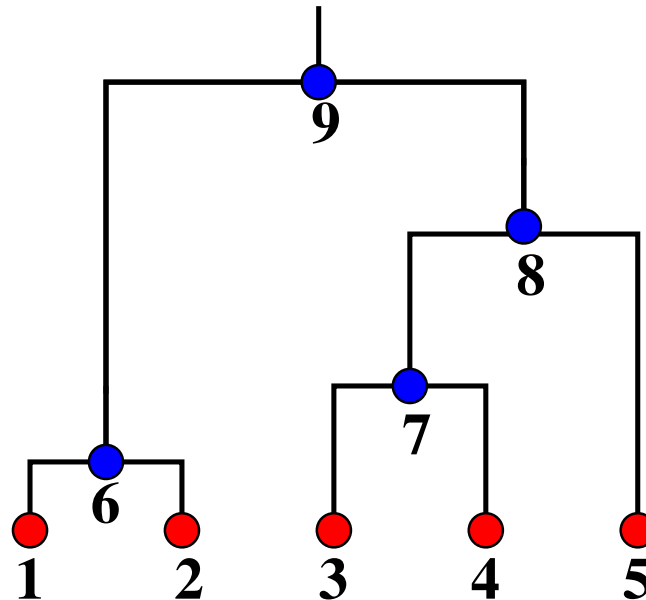
$$(2n - 3)!! = \prod_{i=2}^n (2i - 3) = 1 \cdot 3 \cdot 5 \cdot 7 \cdots (2n - 3)$$

(or  $(2n - 5)!!$  for unrooted trees). For  $n = 20$ : about  $10^{21}$  trees  
→ infeasible even for a relatively small number of species.

**Theorem:** Phylogenetic Tree Construction (for almost all reasonable models) is NP-Complete.

# Number of nodes and edges

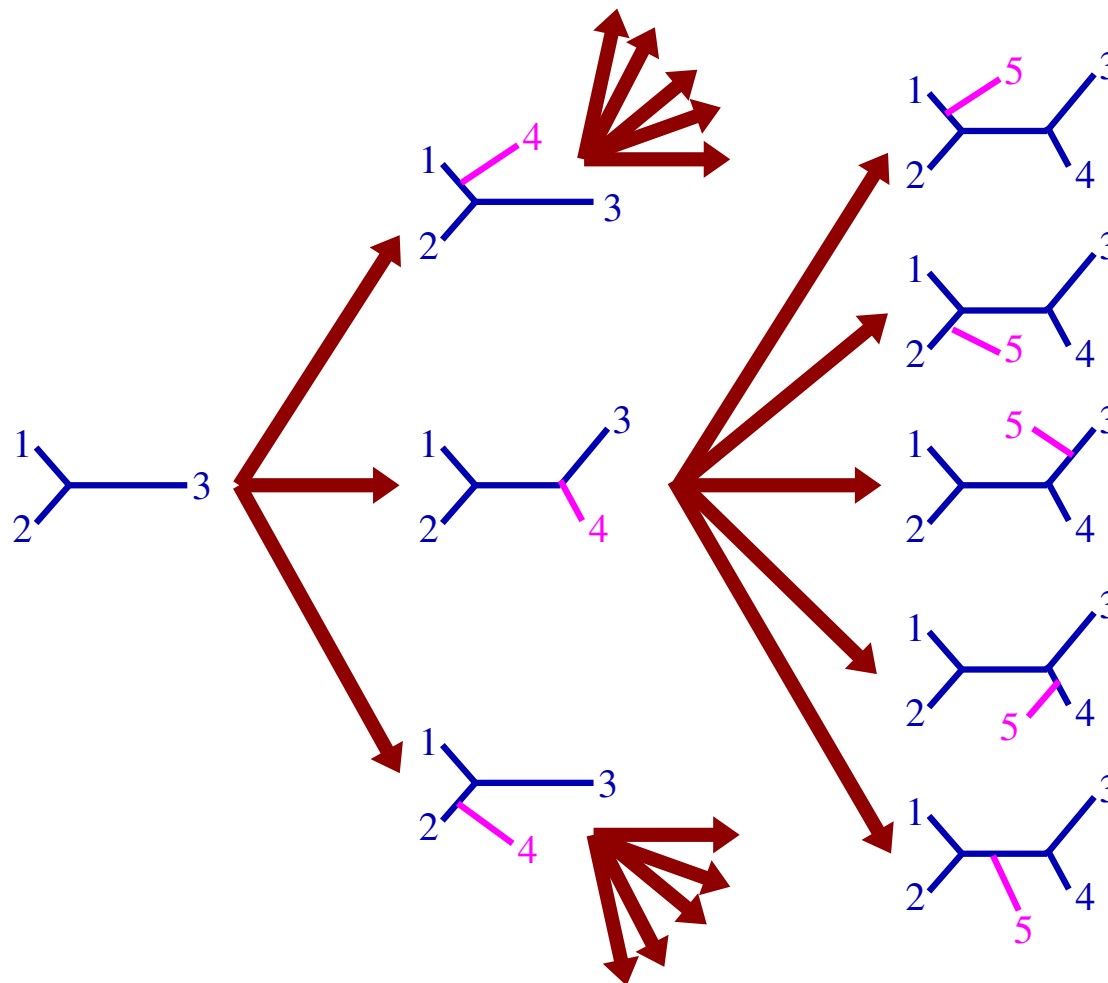
- Suppose there are  $n$  leaves in a **rooted tree**. As we move up the tree, two edges join as a new node is reached. Each time, the number of edges is reduced by one.
- So there must be  $(n - 1)$  inner nodes  $\rightsquigarrow (2n - 1)$  nodes and  $(2n - 2)$  edges (not counting the edge above the root)



- **Unrooted tree:**  $(2n - 2)$  nodes and  $(2n - 3)$  edges.

Consider an **unrooted tree with  $n$  leaf nodes**:

- An **extra edge** with new label at its leaf can be added at any edge  
 $\rightsquigarrow$  there are  $(2n - 3)$  times as many trees with  $n + 1$  leaves.
- Instead of an extra edge, we can **add a root**  
 $\rightsquigarrow$  there are  $(2n - 3)$  times as many rooted trees as unrooted ones.
- There are  $1 \cdot 3 \cdot 5 \cdot \dots \cdot (2n - 5) = (2n - 5)!!$  unrooted trees with  $n$  leaves  
 $\rightsquigarrow (2n - 3)!!$  rooted trees.



# Distance-Based Methods

- Assume we have a **measure of distance** between each pair of species.
- **Approach:** find a tree that predicts the observed set of distances as closely as possible.
- This **leaves out some of the information** contained in the raw sequence (due to reduction to table of pairwise distances).
- It seems that in many cases **most of the evolutionary information** is conveyed in these distances.

# Least Squares Methods

- **Idea:** approximate an observed distance matrix.
- **Goal:** find a tree  $T$ , whose leaves are the  $n$  given species, and that predicts distances  $d_{ij}^T$  between the species, so that the following expression is minimized:

$$SSQ(T) \equiv \sum_{i=1}^n \sum_{j \neq i} (d_{ij} - d_{ij}^T)^2$$

where  $d_{ij}$  is the observed distance between species  $i$  and  $j$ .

- $SSQ$  is a measure of the discrepancy between the **observed distances**  $d_{ij}$  and the **path distances**  $d_{ij}^T$  in the tree  $T$ .

# The Least Squares Tree Problem

**Problem:** Least Squares Tree.

**INPUT:** The distance  $d_{ij}$  between species  $i$  and  $j$ , for each  $1 \leq i, j \leq n$ , arranged in distance matrix  $D$ .

**QUESTION:** Find the phylogenetic tree  $T$ , with the species as its leaves, that minimizes  $SSQ(T)$ .

- Difficult problem, due to optimization over discrete set of topologies. One can show: NP-complete problem.
- Two polynomial heuristics - *UPGMA* and *Neighbor-Joining*. These are efficient algorithms, but they will only work in some particular cases.

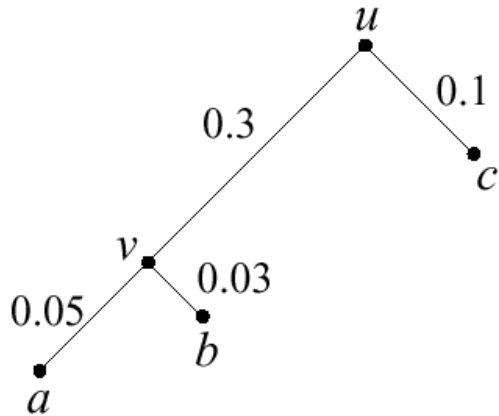
**Ultrametric trees:** All the leaves have the same distance to the root  $\rightsquigarrow$  all species evolve at the same rate.

**In such cases, UPGMA will find the correct topology.**

# Efficiently solvable Special Cases

**Additive distance matrices:** There exists a tree that represents **exactly** the given distances between species:

$d_{ij} = \sum$  of all edge lengths in the path between leaves  $i$  and  $j$ .



	a	b	c
a	0	0.08	0.45
b	0.08	0	0.43
c	0.45	0.43	0

**In such cases, neighbor joining will find the correct topology.**

In general, given a set of pairwise distances ( $\rightsquigarrow$  scales **quadratically** in  $n$ ) it is not possible to find a set of internal edges ( $\rightsquigarrow$  number is **linear** in  $n$ ) that explain all the observed distances as path distances in the tree.

# UPGMA

- **UPGMA**, or *Unweighted Pair Group Method with Arithmetic mean*, is a heuristic algorithm that often generates satisfactory results.
- The algorithm iteratively **joins the two nearest clusters** (or groups of species), until one cluster is left.

## Initialization:

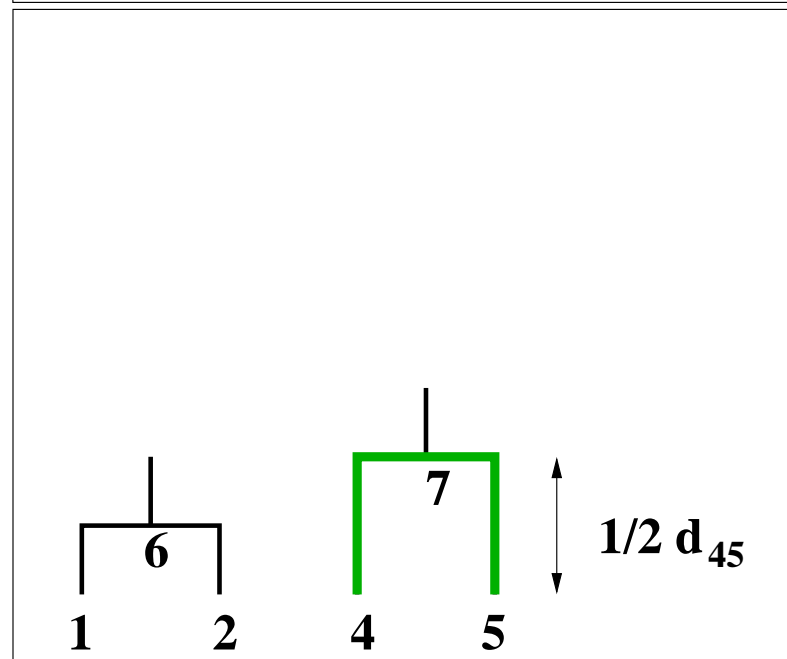
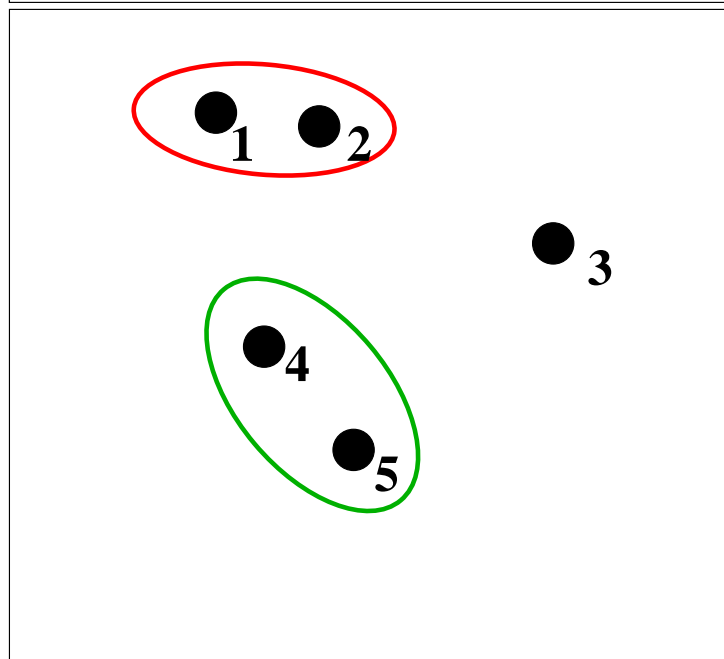
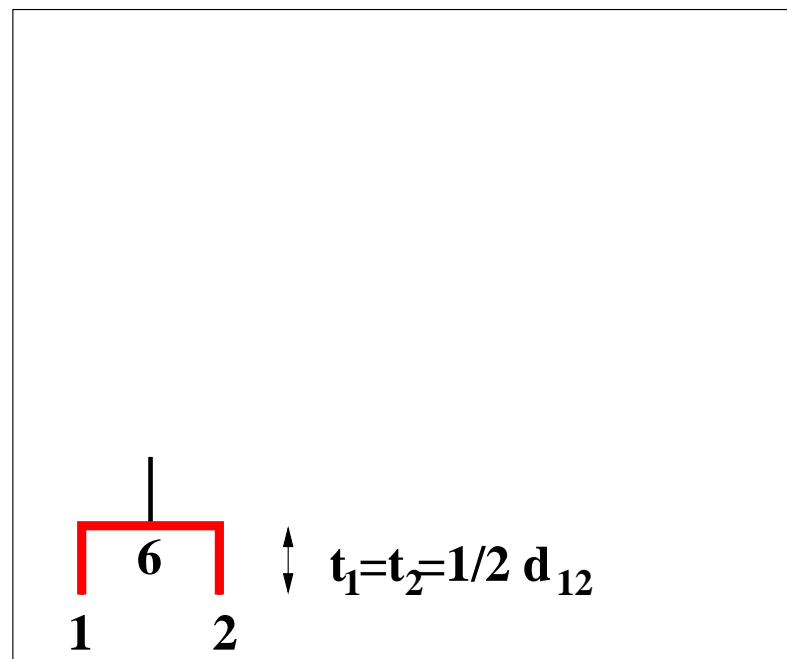
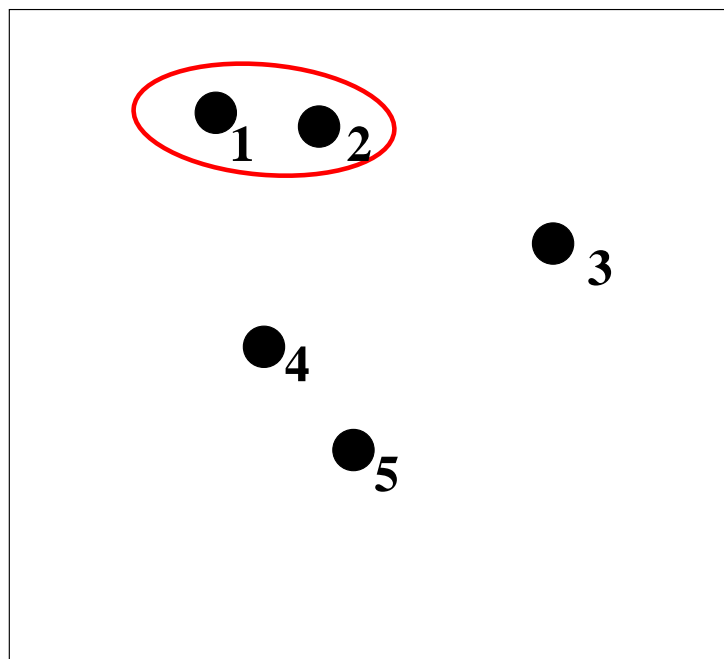
1. Initialize  $n$  clusters  $C_i$ , one species per cluster.
2. Set the size of each cluster to 1:  $n_i \leftarrow 1$ .
3. In the output tree  $T$ , assign a leaf for each species.

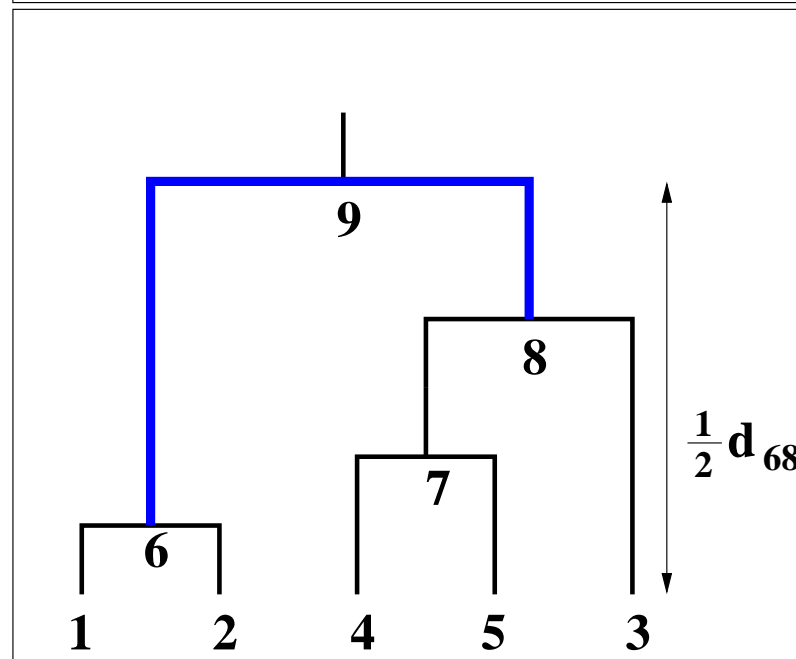
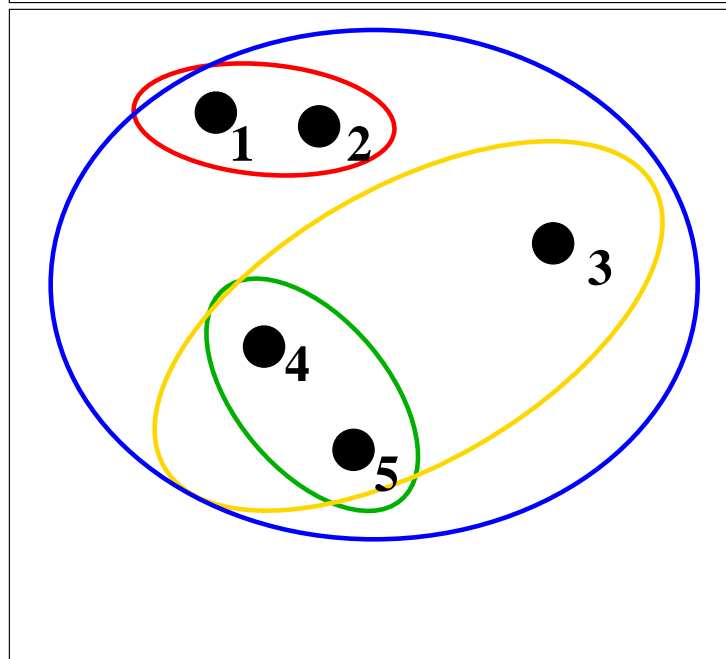
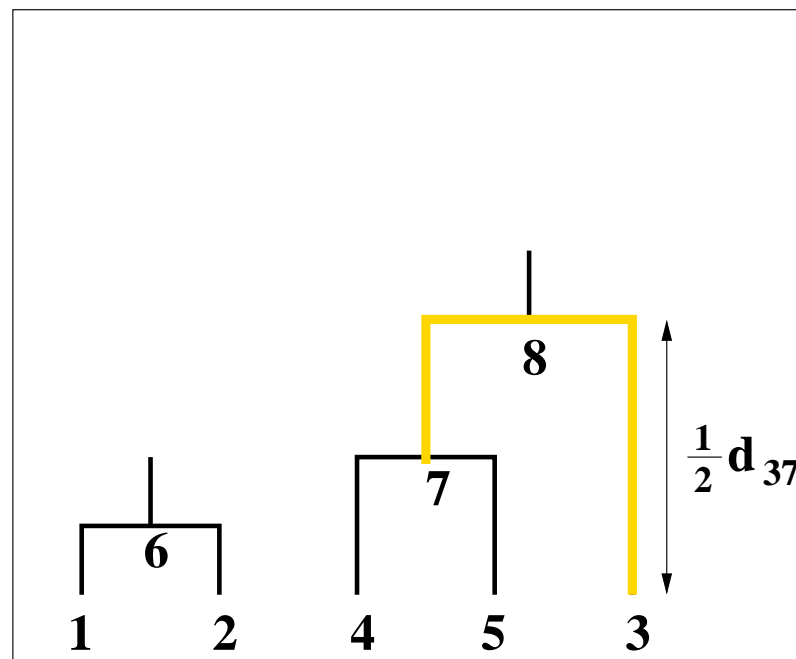
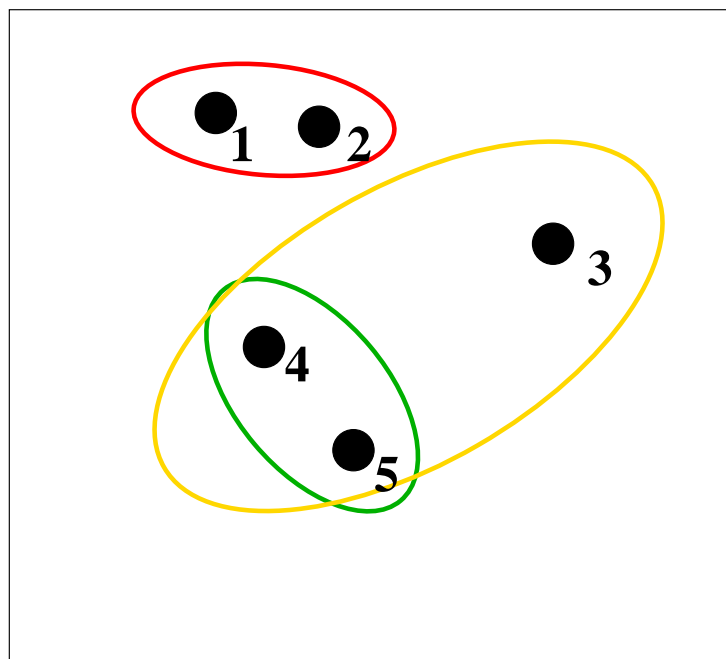
## Iteration:

1. Find the  $i$  and  $j$  that have the smallest distance  $d_{ij}$ .
2. Create a new cluster -  $k$  by  $C_k = C_i \cup C_j$  and compute the distance from the new cluster to all other clusters as a weighted average of the distances from its components:

$$d_{kl} = \left(\frac{n_i}{n_i + n_j}\right)d_{il} + \left(\frac{n_j}{n_i + n_j}\right)d_{jl}.$$

3. Connect  $i$  and  $j$  on the tree to the new node  $k$ , and place it at height  $d_{ij}/2$ . Note: vertical axis represents time. Horizontal connections do not contribute to path-length computations.
4. Delete the columns and rows in  $D$  that correspond to clusters  $i$  and  $j$ , and add a column and row for cluster  $k$ .
5. Return to 1 until there is only one cluster left.





# UPGMA: Analysis

- A metric on a set of objects  $O$  is given by the assignment of a real number  $d(x,y)$  to every pair  $x, y \in O$  where  $d(x,y)$  has to fulfill the following requirements:

$$d(x, y) > 0 \quad \text{for } x \neq y, \quad d(x, y) = 0 \quad \text{for } x = y$$

$$d(x, y) = d(y, x)$$

$$d(x, y) \leq d(x, z) + d(z, y) \quad \forall x, y, z \quad (\text{triangle inequality})$$

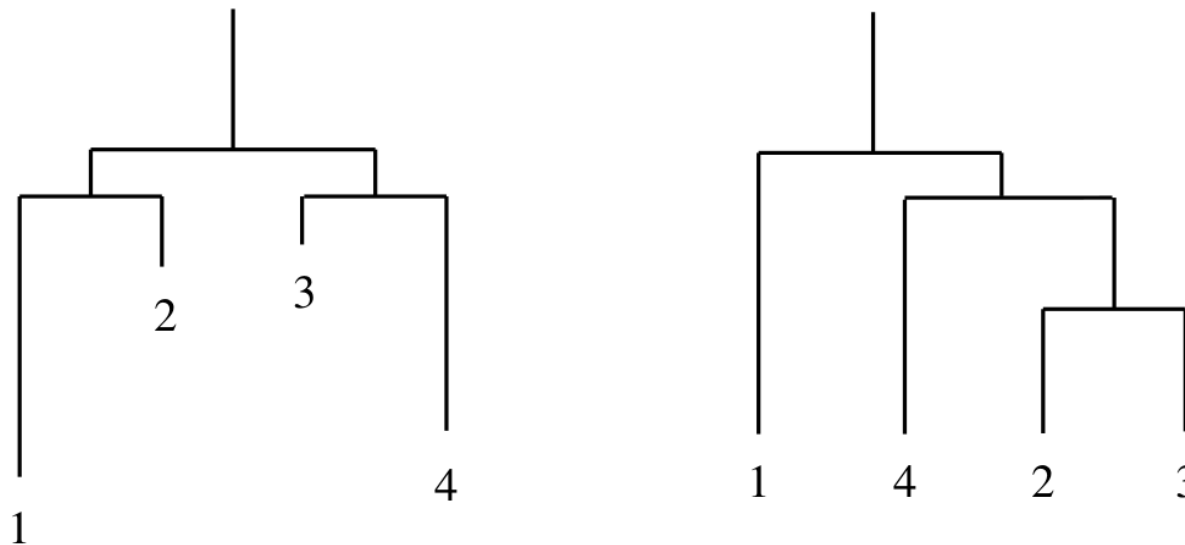
- An ultrametric has to fulfill a restricted triangle inequality

$$d(x, y) \leq \max (d(x, z), d(y, z)).$$

- A **clocklike**, or **ultrametric** tree is a rooted tree, in which the total branch length from the root to any leaf is equal  
→ **molecular clock** that ticks in a constant pace, and all the observed species are at an equal number of ticks from the root.

# UPGMA: Analysis

- One can show: If the input data are ultrametric then UPGMA is **guaranteed to return the optimal solution**.
- For substantially **non-clocklike** trees, the algorithm might give seriously **misleading results**.



**Figure 7.5** *A tree (left) that is reconstructed incorrectly by UPGMA (right).*

# Additive trees

- **Ultrametric tree:**
  - $\#(\text{mutations}) \propto \text{temporal distance}(\text{node}, \text{ancestor})$ ,
  - mutations took place with the same rate in all paths.
- But it's a fact, that the evolutionary clock is running **differently** for different species (and even for different regions in a sequence).
- Generalization: **additive trees** (i.e. trees built from additive distance matrices). Unrooted tree, reflection of our ignorance as to where the common ancestor lies.
- All nodes (except for the leaves) have degree three  
     $\rightsquigarrow$  **unrooted binary tree**. More general, but undirected.

# Additive distance matrix

Distance matrix  $D$  is additive iff there exists a tree  $T$  with  $d_{ij}^T = d_{ij}$   
 $\rightsquigarrow SSQ(T) = \sum_{i=1}^n \sum_{j \neq i} (d_{ij} - d_{ij}^T)^2 = 0$ .

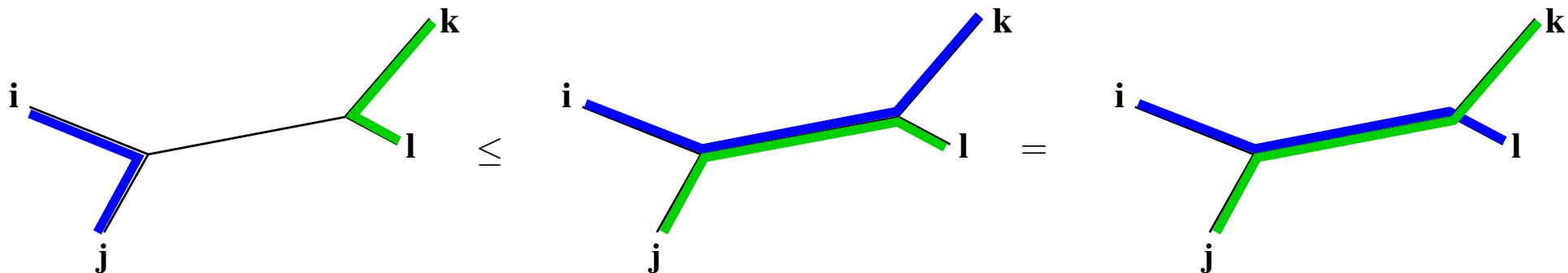
**Every ultrametric is additive, but the converse is not true.**

Simple test for additivity?

**Four point condition:** For every set of four leaves  $i, j, k$  and  $l$ , two of the distances  $d_{ij} + d_{kl}$ ,  $d_{ik} + d_{jl}$  and  $d_{il} + d_{jk}$  must be equal and larger than the third. For instance

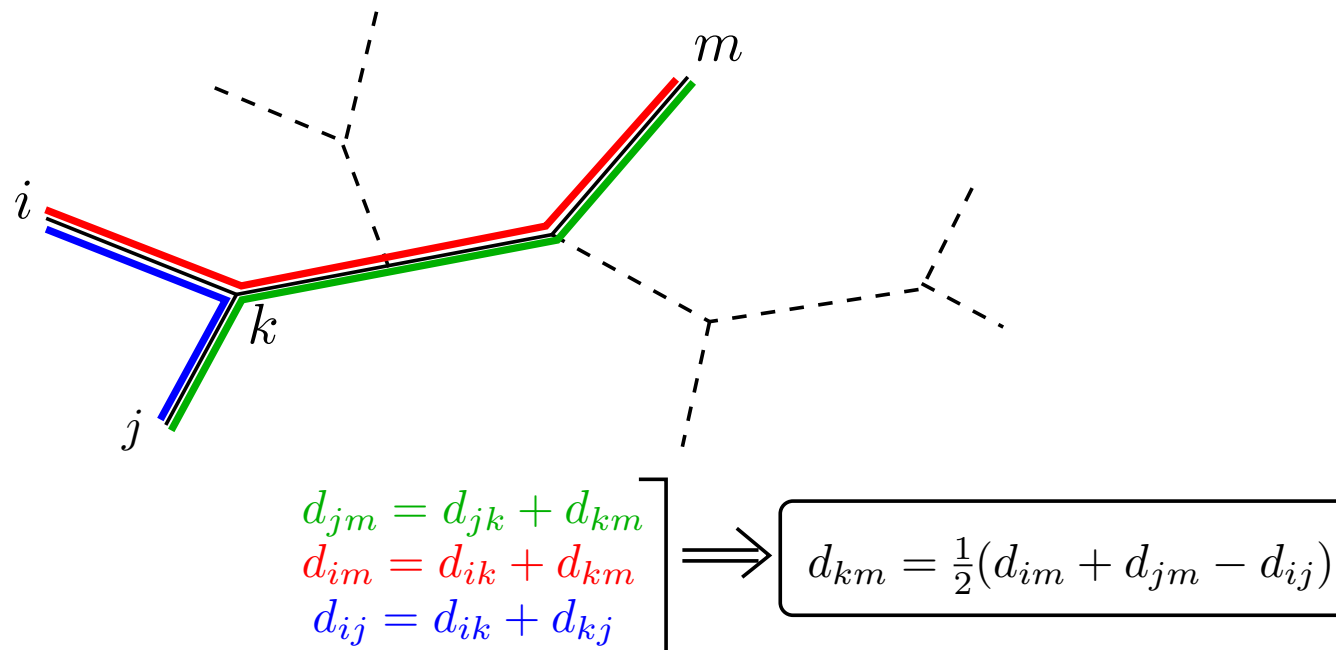
$$d(i, j) + d(k, l) \leq d(i, k) + d(j, l) = d(i, l) + d(j, k).$$

Generalizes the triangle inequality (take  $k = l$ ).



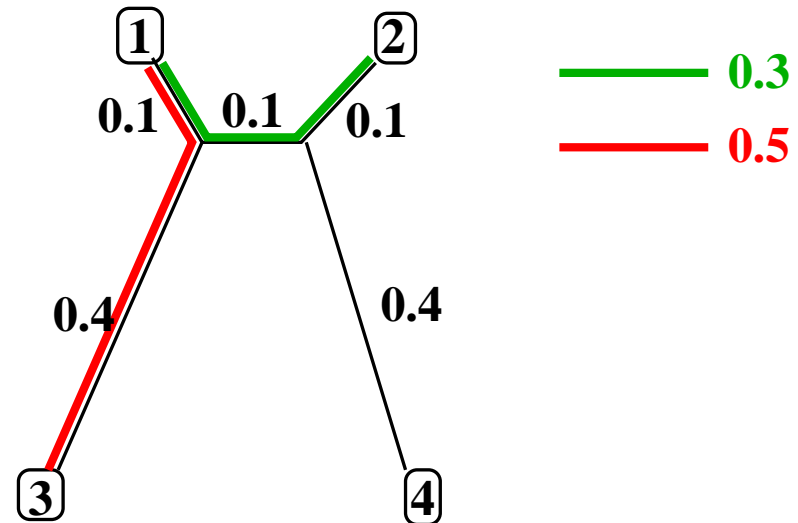
# Neighbor Joining

- Neighbor-Joining approximates the least squares tree, assuming **additivity**, but **without resorting to the assumption of a molecular clock**.
- **Idea:** Find direct ancestor of two species, join them, iterate.
- **Distance computation:** Assume we join  $i$  and  $j$  with ancestor  $k$  → remove  $i, j$  from list of leaves → add  $k$  to list with distances to other leaves  $m$  defined as  $d_{km} = \frac{1}{2}(d_{im} + d_{jm} - d_{ij})$ .



# Correcting distances

**Problem:** it is not sufficient to pick simply the two closest leaves.



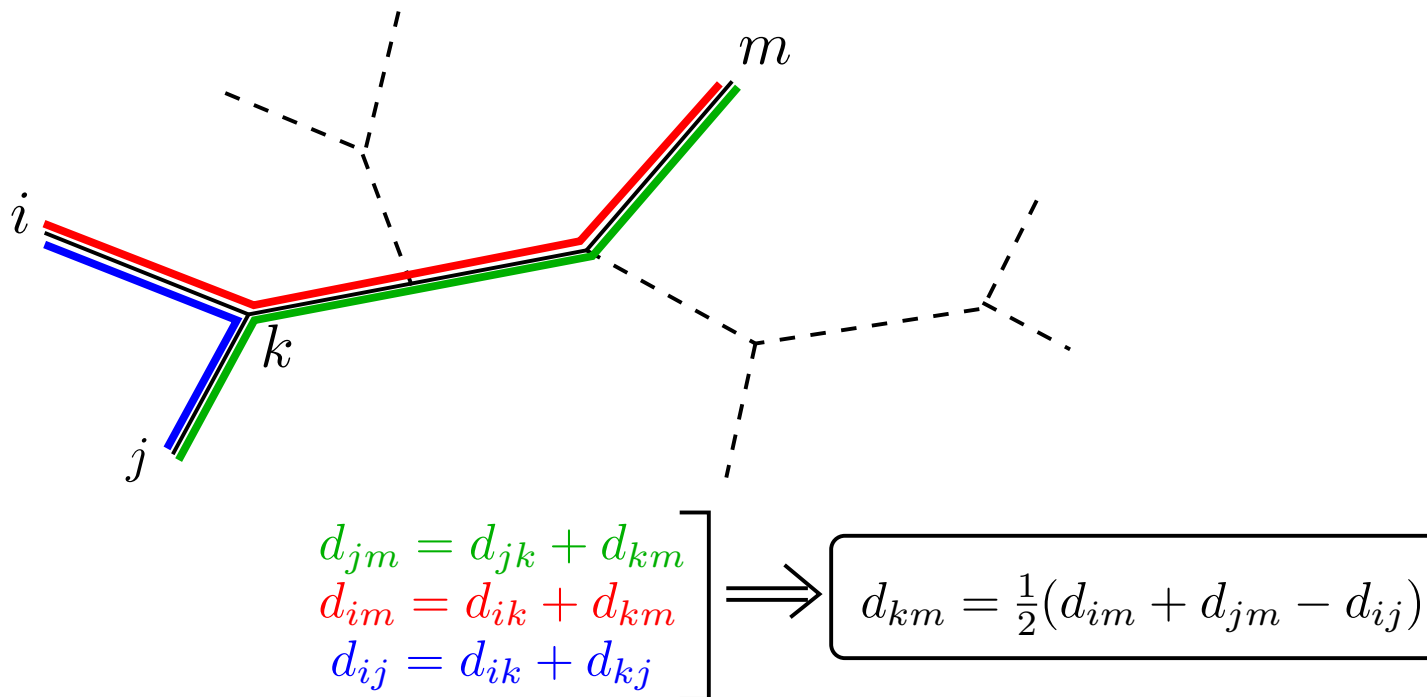
**Solution:** Join clusters that are not only close, but are also far from the rest. For node  $i$ , define average distance  $u_i$  to all other leaves:  $u_i = \sum_{k \neq i} \frac{d_{ik}}{(n-2)}$ , and “correct” distances:  $q_{ij} = d_{ij} - (u_i + u_j)$ .

$$D = \begin{bmatrix} 0 & 0.3 & 0.5 & 0.6 \\ & 0 & 0.6 & 0.5 \\ & & 0 & 0.9 \\ & & & 0 \end{bmatrix}, \quad Q = \begin{bmatrix} * & -1.1 & -1.2 & -1.1 \\ & * & -1.1 & -1.2 \\ & & * & -1.1 \\ & & & * \end{bmatrix}$$

# Neighbor Joining Theorem

(Studier & Keppler, Molecular Biology and Evolution 5:729-731, 1988): For a tree with additive lengths,  $q_{ij}$  minimal implies  $i, j$  are neighboring leaves.

We know how to compute the branch lengths from a new node  $k$  to all other nodes  $m \neq (i, j)$ .



# Neighbor-Joining: Distance Computation

What about  $i$  and  $j$ ?  $d_{ik} = \frac{1}{2}(d_{ij} + d_{im} - d_{jm}), \forall m \neq (i, j)$ .

If observed distances are indeed fully additive, we can pick any  $m \neq (i, j)$ . In practice, it might be better to average:

$$\begin{aligned} d_{ik} &= \frac{1}{2}(d_{ij} + d_{im} - d_{jm}), \forall m \neq (i, j) \Rightarrow \text{average over } m \Rightarrow \\ &= \frac{1}{2} \cdot \frac{1}{n-2} \sum_{m \neq (i, j)} (d_{ij} + d_{im} - d_{jm}) \\ &= \frac{1}{2}d_{ij} + \frac{1}{2} \cdot \frac{1}{n-2} \sum_{m \neq (i, j)} (\overbrace{q_{im} + u_i + u_m}^{d_{im}} - q_{jm} - u_j - u_m) \\ &= \frac{1}{2}(d_{ij} + u_i - u_j) + \frac{1}{2} \cdot \frac{1}{n-2} \cdot \underbrace{\sum_{m \neq (i, j)} (q_{im} - q_{jm})}_{=0} \end{aligned}$$

## Neighbor-Joining algorithm: Initialization:

1. Initialize  $n$  clusters with the given species, one species per cluster.
2. Set the size of each cluster to 1:  $n_i \leftarrow 1$ .
3. In the output tree  $T$ , assign a leaf for each species.

## Iteration:

1. For each species, compute  $u_i = \sum_{k \neq i} \frac{d_{ik}}{(n-2)}$
2. Choose the  $i$  and  $j$  for which  $d_{ij} - u_i - u_j$  is smallest.
3. Join clusters  $i$  and  $j$  to new cluster, with corresponding node  $k$  and set

$$d_{km} = \frac{1}{2}(d_{im} + d_{jm} - d_{ij}) \quad \forall m \neq (i, j) \in \text{Nodes}(T).$$

Calculate the branch lengths from  $i$  and  $j$  to the new node as:

$$d_{ik} = \frac{1}{2}(d_{ij} + u_i - u_j) \quad , \quad d_{jk} = \frac{1}{2}(d_{ij} + u_j - u_i).$$

4. Delete clusters  $i$  and  $j$  from  $T$  and add  $k$ .
5. If more than two nodes remain, go back to 1. Otherwise, connect the two remaining nodes by a branch of length  $d_{ij}$ .

# Reconstructing Trees from Non-additive Matrices

- Q: What if the distance matrix is **not** additive?
- A: We could still run NJ!
- Q: But can **anything** be said about the resulting tree?
- A: Not really. Resulting tree topology could even vary according to way **ties are resolved** on the way.

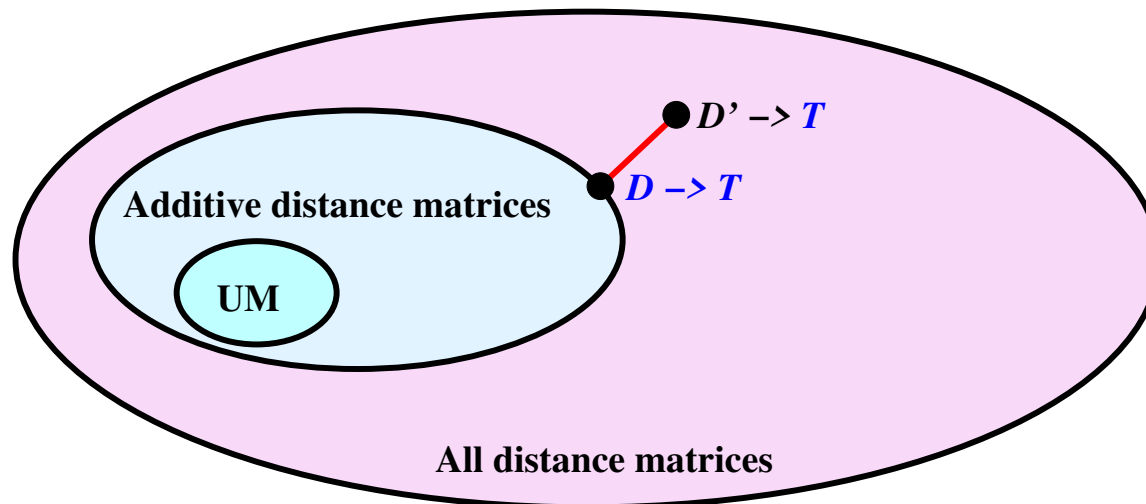
# Almost Additive Distance Matrices

A distance matrix  $D'$  is called “**almost additive**” if there exists an additive matrix  $D$  (with corresponding tree  $T$ ) such that

$$|D - D'|_{\infty} = \max_{i,j} \{|d_{i,j} - d'_{i,j}|\} \leq \min_e \{l(e)/4\},$$

where  $e$  is an edge in the tree  $T$  (corresponding to the additive matrix  $D$ ) with length  $l(e)$ .

**Theorem:** If  $D'$  is almost additive with respect to a tree  $T$ , then the output of NJ is a tree  $T'$  with the **same topology** as  $T$ .



# Character Based Methods

**Problem:** Optimal Phylogenetic Tree. **INPUT:**

- A set of  $n$  **species**.
- A set of  $m$  **characters** pertaining to all of these species,
- For each species, the **values** of each of the characters.
- **Notation:**  $n \times m$  matrix  $M$ , where  $M_{i,j}$  represents the value of the  $j$ -th character of the  $i$ -th species. The **value** of each character is taken from a known alphabet  $\Sigma$ .

**Question:** What is the fully labeled phylogenetic tree that best explains the data, i.e., maximizes some target function.

**Limiting assumptions:** (probably not exactly correct in practice)

- Characters are **mutually independent** ( $\rightarrow$  change in one character has no effect on the distribution of another character).
- After two species diverged in the tree, they **continue to evolve independently**.

# Character-based Methods: Parsimony

- Intuitive **score** for tree: **number of changes** along edges.
- Minimizing this score is called **parsimony**.

**Notation:**  $V(T)$ : **vertices** of a tree,  $E(T)$ : **edges**.

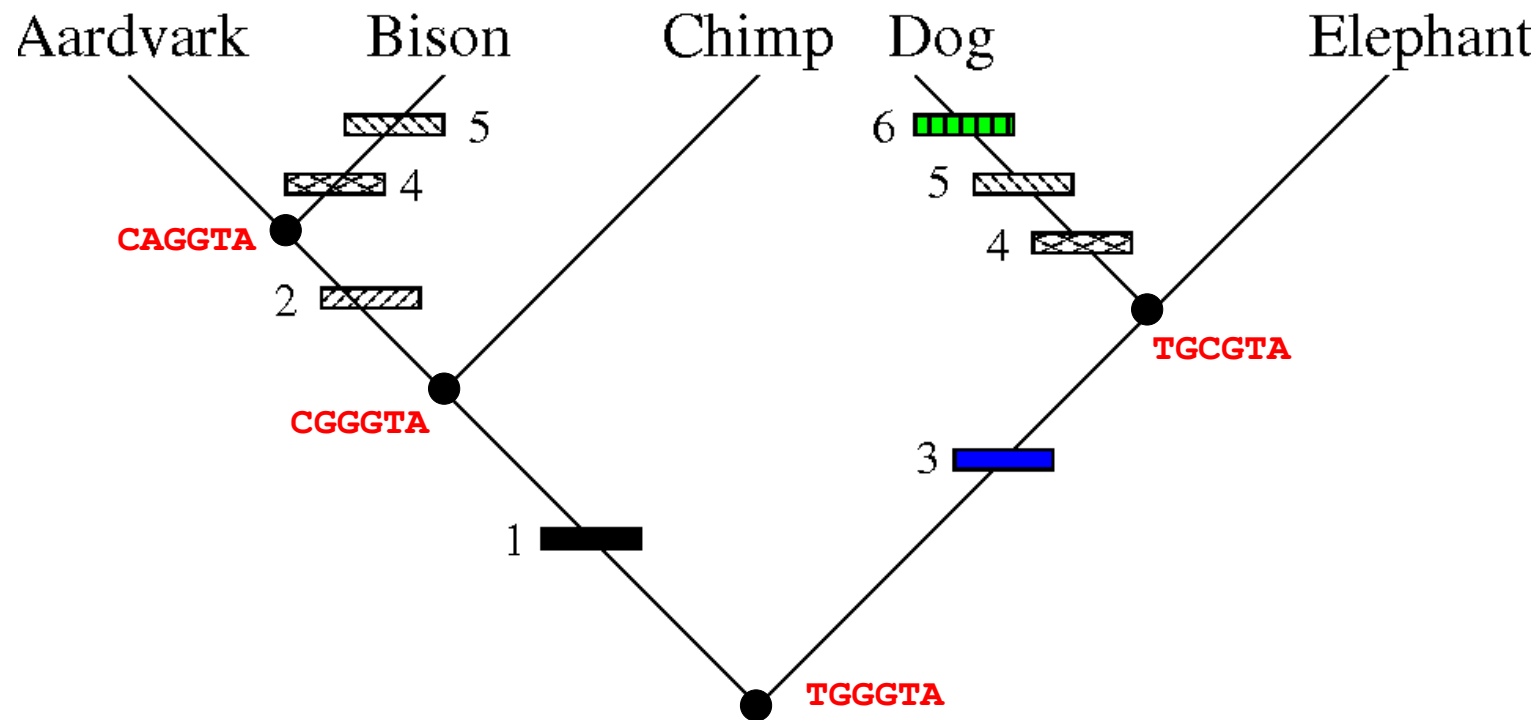
$v_j$ : **value** of  $j$ -th character at vertex  $v \in V(T)$ .

Given a phylogenetic tree  $T$ , its **parsimony score** is defined as

$$S(T) = \sum_{(v,u) \in E(T)} |\{j : v_j \neq u_j\}|$$

That is - the total number of times the **value of some character changes** along some edge.

# Most parsimonious 5-species phylogeny for 6 characters:



Adapted from Figure 8.8 in R. Shamir, Orly Stettiner, R. Gabor: Algorithms for Molecular Biology 8.1 Preface:  
Phylogenetics and Phylogenetic Trees

	1	2	3	4	5	6
Aardvark	C	A	G	G	T	A
Bison	C	A	G	A	C	A
Chimp	C	G	G	G	T	A
Dog	T	G	C	A	C	T
Elephant	T	G	C	G	T	A

# Weighted Small Parsimony

- Cost of a change is not necessarily constant:  
 $C_{ij}^c$  = cost of the character  $c$  changing from state  $i$  to state  $j$ .
- **Goal:** minimize the total cost of the tree given the topology and the leaf labels.

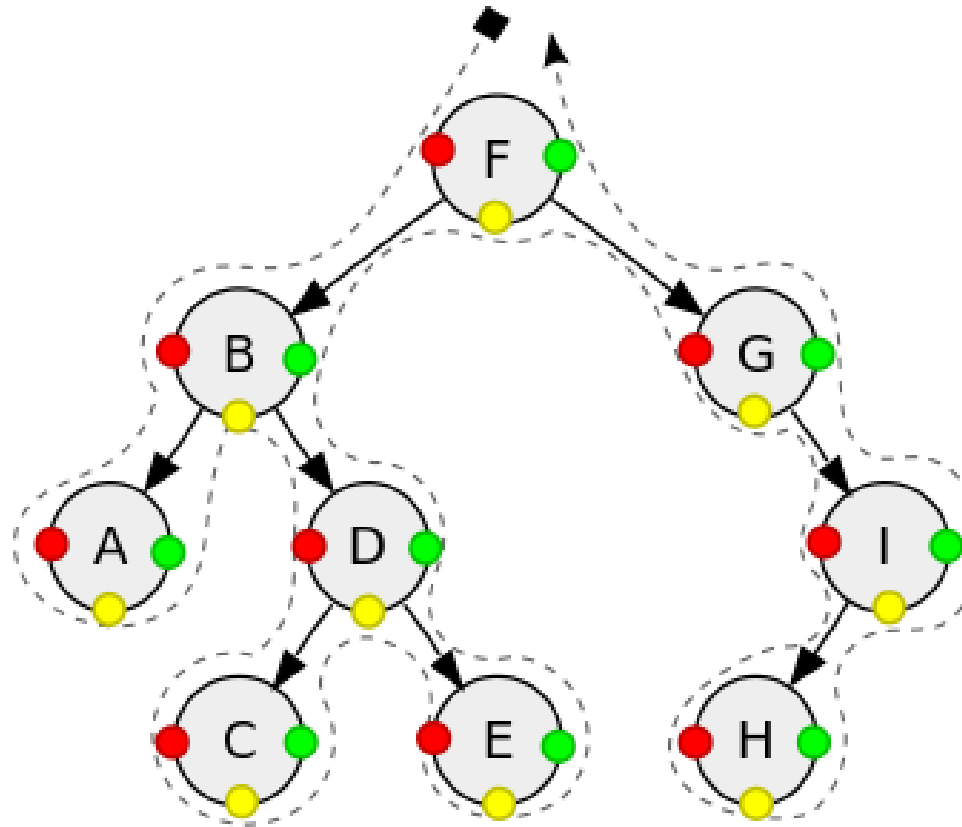
**Problem:** Weighted Small Parsimony.

**INPUT:** The topology of a rooted phylogenetic tree with leaves having labels in  $\Sigma$ . The costs  $C_{ij}^c$  for  $i, j \in \Sigma$ . There are  $k$  possible character values,  $|\Sigma| = k$ .

**QUESTION:**

1. What is the minimum possible cost for this topology?
2. What is the optimal labeling of the internal nodes?

# Recall: Tree traversals



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Depth-first traversal of an example tree:

pre-order (red): F, B, A, D, C, E, G, I, H

in-order (yellow): A, B, C, D, E, F, G, H, I

post-order (green): A, C, E, D, B, H, I, G, F.

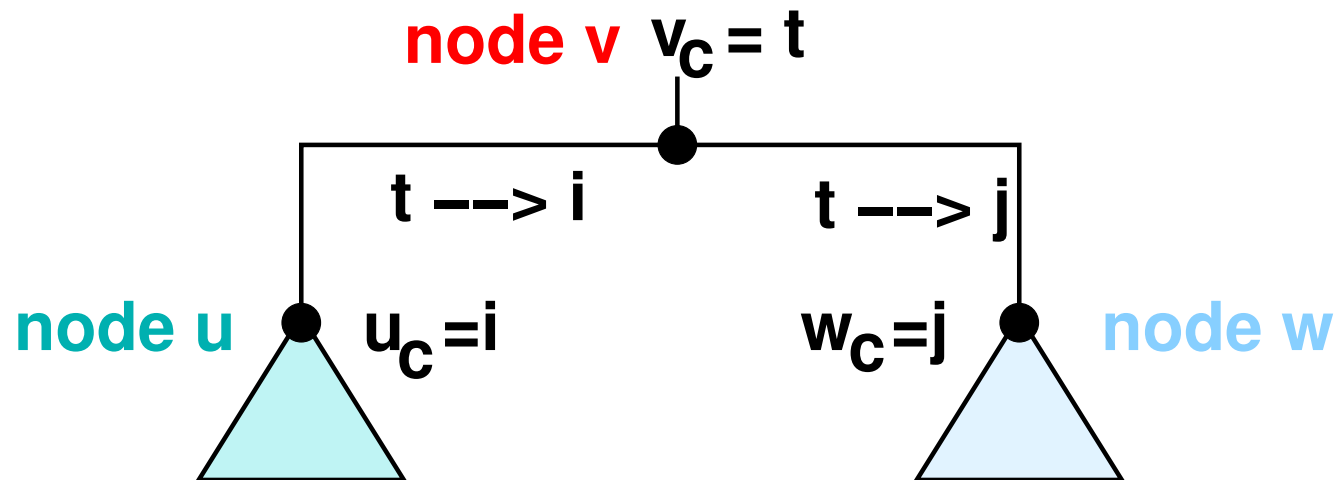
# Sankoff's algorithm

**Step 1:** for each node  $v$  and each state  $t$  compute quantity  $S_t^c(v)$ : minimum cost of the subtree whose root is  $v$ , assuming that the character value at  $v$  is  $t$ , i.e.  $(v_c = t)$ . **In postorder:** for each leaf  $v$ :

$$S_t^c(v) = \begin{cases} 0 & v_c = t \\ \infty & \text{otherwise} \end{cases}$$

For an internal node  $v$ , with subnodes  $u$  and  $w$ :

$$S_t^c(v) = \min_i \{C_{ti}^c + S_i^c(u)\} + \min_j \{C_{tj}^c + S_j^c(w)\}$$



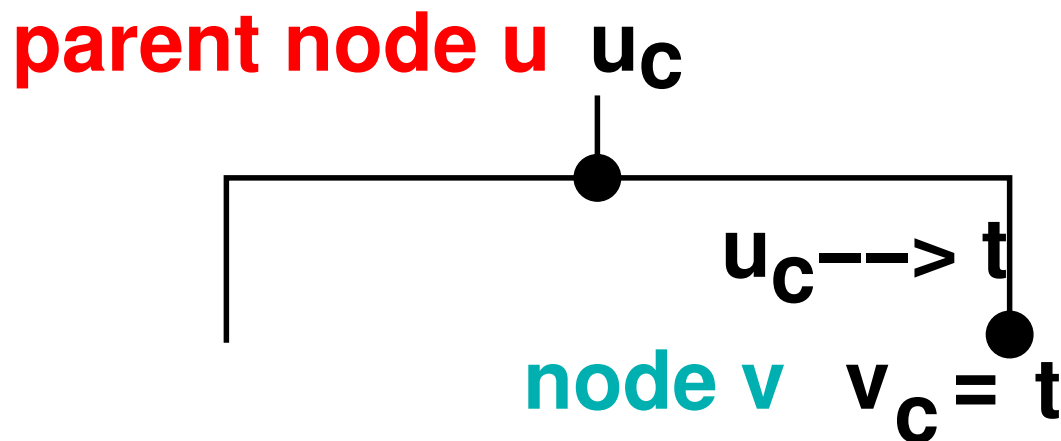
# Sankoff's algorithm

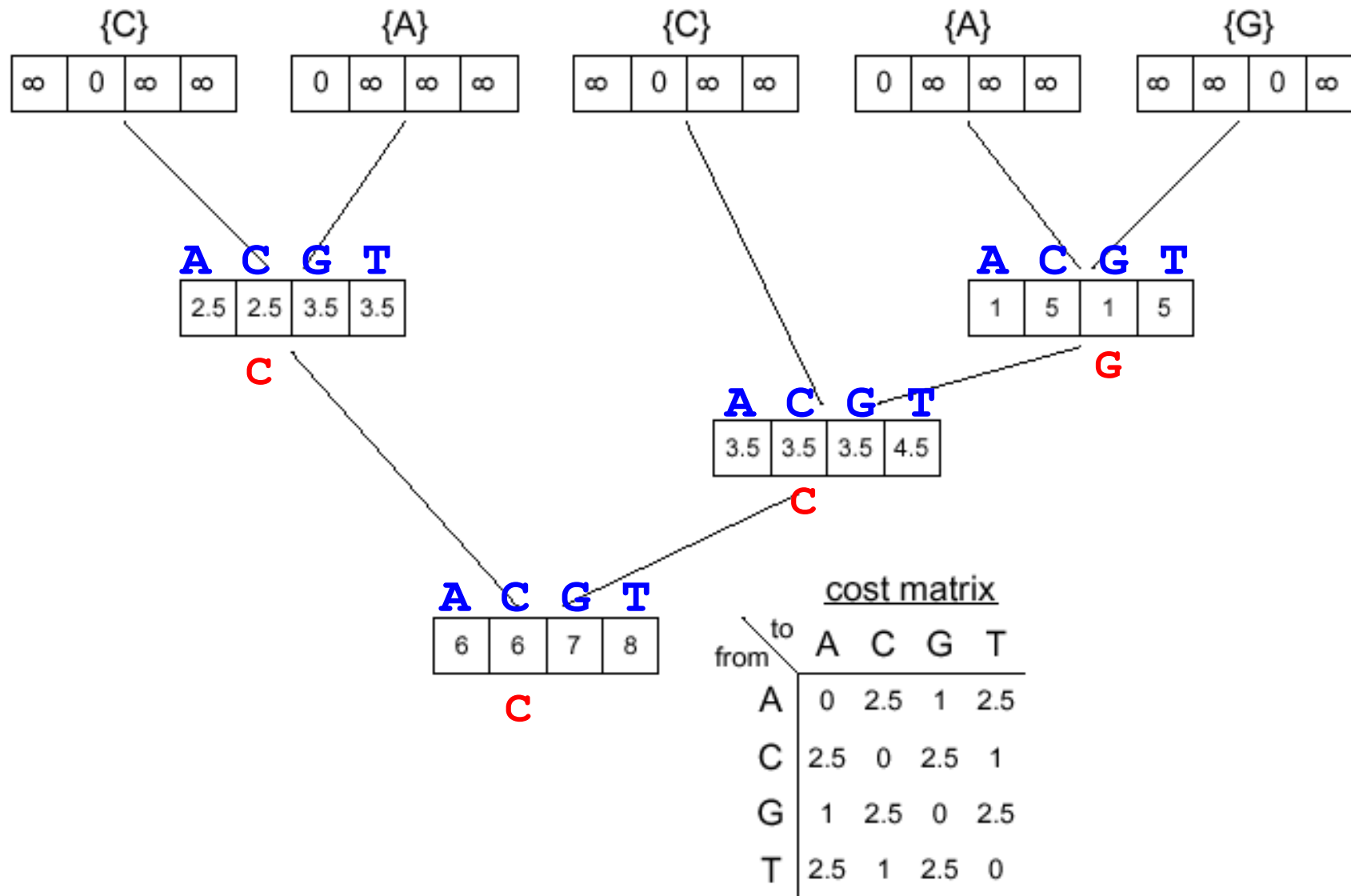
For  $m$  characters, minimum total cost of a tree with root  $r$ :

$$S(T) = \sum_{c=1}^m \min_t S_t^c(r)$$

**Step 2:** Based on  $S_t^c(v)$ , determine the **optimal values for each character** in internal nodes. **Preorder:** For the root node  $r$ , choose character value  $r_c = \arg \min_t S_t^c(r)$ . For any other node  $v$ , with parent node  $u$ ,

$$v_c = \arg \min_t (C_{uct}^c + S_t^c(v))$$





Adapted from Figure 8.10 in R. Shamir, Orly Stettiner, R. Gabor: Algorithms for Molecular Biology 8.1 Preface:  
Phylogenetics and Phylogenetic Trees

# Large Parsimony

**Final goal:** find the optimal phylogeny, not just the optimal internal labeling of a given phylogeny.

**Problem:** Large Parsimony.

**INPUT:** A matrix  $M$  describing  $m$  characters of a set of  $n$  species,

**QUESTION:** What is the optimal phylogeny for these species, i.e., the one minimizing the parsimony score?

**Remark:** weighted and a non-weighted version, but difference is not essential. It can be shown that this **problem is NP-hard**. However, several approximation heuristics exist.

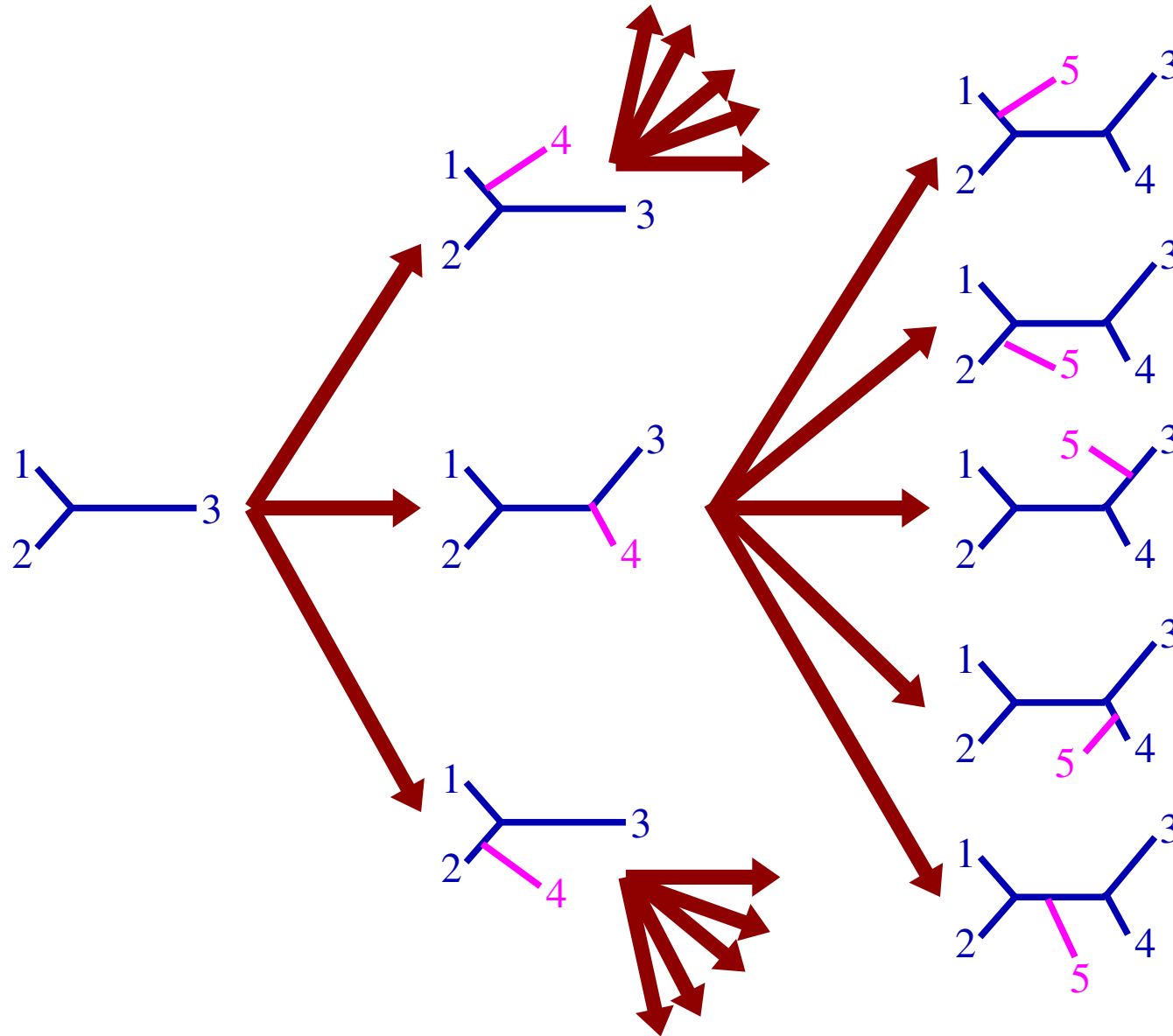
# Branch and Bound

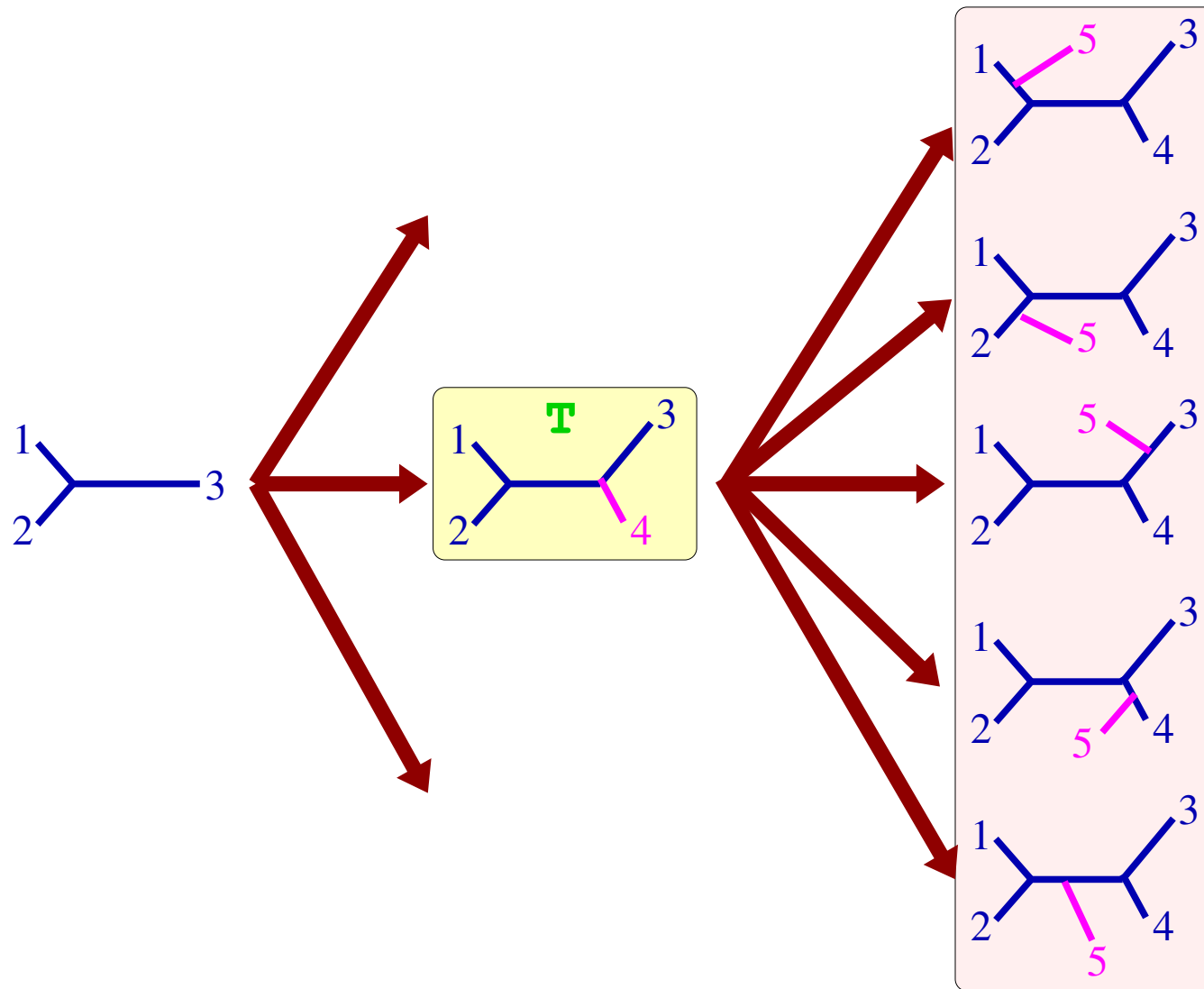
- **Branch-and-Bound** (B&B) deals with optimization problems over a **search space** that can be presented as the **leaves of a tree**.
- First used for parsimony by (Hendy and Penny, 1982).
- Works when the **search tree is monotonous**: the score of each node in the search tree is at least as bad as that of any of its ancestors.
- B&B is **guaranteed to find the optimal solution**, but its complexity in the worst case is as high as that of exhaustive search.
- Basic version: Tree is traversed in some order, cost of the best leaf found so far is kept as a bound  $C'$ . When a node is reached whose cost is  $C > C'$ , the tree is **pruned at that node**.

# Branch and Bound for Parsimony

- **Parsimony:** present the search-space as a search tree:
  - $k$ -th level of search tree: nodes represent all possible phylogenetic trees with  $k$  leaves for the first  $k$  species,
  - Children of such a node: all phylogenetic trees created by adding the  $(k + 1)$ -th species.
- Search tree is **monotonous**, since adding a node to a given tree can **never reduce** its parsimony score.
- **Does not lower worst-case time complexity.** However, in real-life test cases it proved to speed up the search considerably.
- Plausible strategy: Start with distance-based approach.  
Neighbor joining  $\rightsquigarrow$  initial topology  $T'$   $\rightsquigarrow$  compute its parsimony cost  $C'$   $\rightsquigarrow$  use this as initial bound.

# Branch and Bound for Parsimony (cont'd)





**If** partial tree **T** has  $cost = C$ ,  
 & the best complete tree seen has  $cost = C' < C$   
**Then** prune expansions of **T**

# Maximum Likelihood Methods

- Given a tree, we often wish to have a statistical measure of how well it describes our data.
- **Likelihood function:**  $P(\text{Data}|\text{Parametrized model})$ , treated as a function of the parameters.
- In our case, the model is a phylogenetic tree, parametrized by its topology  $T$  and the set of edge lengths  $t$ , representing biological time, or genetic distance, between two connected nodes.
- **Problem 1:** For a set of species with observed values  $M$ , what is the likelihood score of a given tree  $(T, t)$ ?
- **Problem 2 (Maximum likelihood inference):** What is the tree that maximizes  $P(M|T, t)$ , i.e. best explains the observations?

# Computing the Likelihood of a Tree

- **Labels** are the sets of  $m$  character values associated with each species, or node in the tree.
- A **reconstruction** is a full labeling of the tree's internal nodes.
- A **branch length**  $t_{vu}$  measures the biological time, or genetic distance, between the species associated with these nodes.
- **Assumptions:**
  - characters are pairwise independent,
  - branching is a **Markov process**: probability of a node having a given label is a function only of the **state of its parent node and the branch length  $t$  between them**.
  - character frequencies are fixed throughout the evolutionary history, and that they are given as  $P(x)$ .

# The Maximum Likelihood Problem

**Problem:** Likelihood of a Tree.

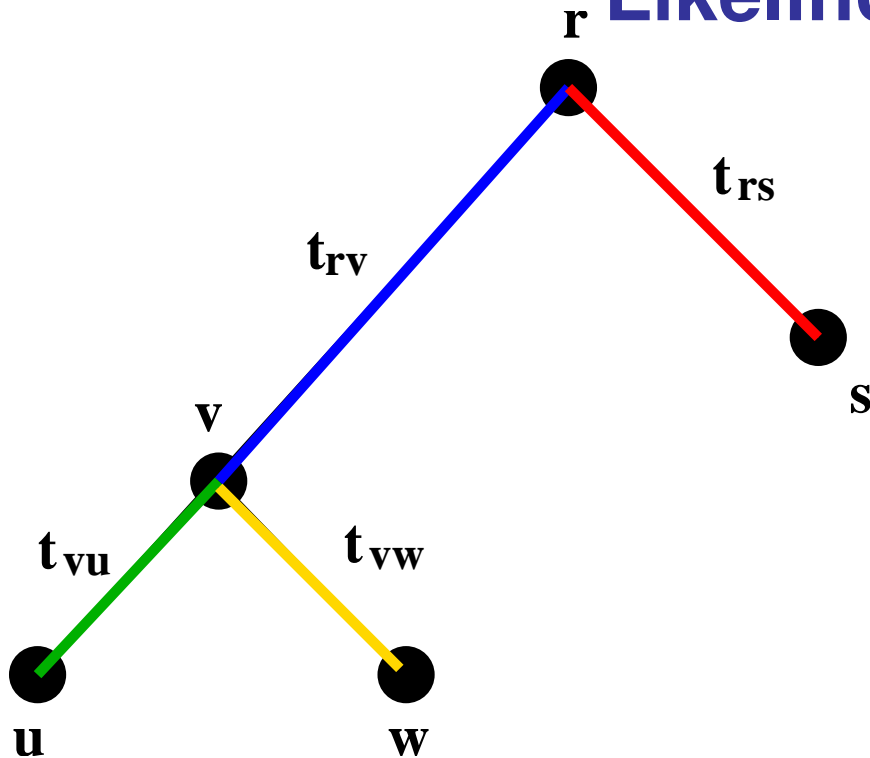
**INPUT:**

- A matrix  $M$  describing a set of  $m$  characters for each one of  $n$  given species.
- A tree with given topology  $T$ , with the above species as the leaves and with known branch lengths  $t_{vu}$ .

**QUESTION:** Calculate the likelihood  $L$  of the tree, assuming the  $m$  characters are independent:

$$L = P(M|T, t) = \prod_{\text{character } j} P(M_j|T, t)$$

# Likelihood of a tree



Labels of internal nodes are unknown  $\rightsquigarrow$  sum over all possible reconstructions (=labelings of internal nodes).

$$L = \sum_r \sum_v P(r) \cdot P_{r \rightarrow s}(t_{rs}) \cdot P_{r \rightarrow v}(t_{rv}) \cdot P_{v \rightarrow u}(t_{vu}) \cdot P_{v \rightarrow w}(t_{vw})$$

Multiple independent characters:

$$L = \prod_{\text{character } j} P(M_j | T, t) = \prod_{\text{character } j} \left\{ \sum_{\text{reconstruction } R} P(r) \cdot \prod_{\text{edges}} P_{u \rightarrow v}(t_{uv}) \right\}$$

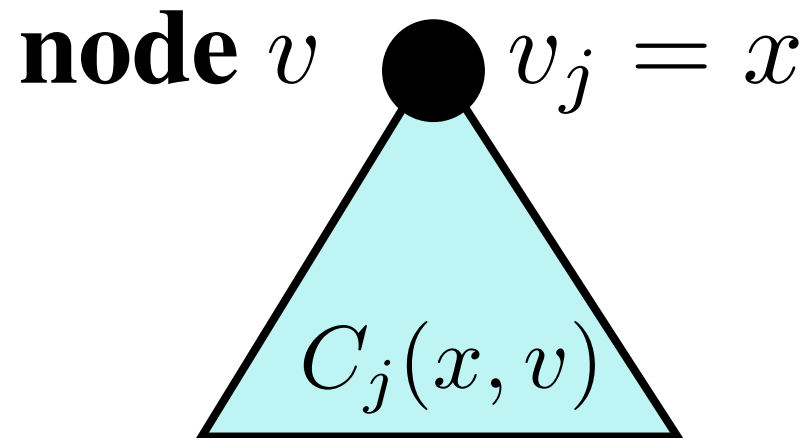
# Computing the Likelihood

Dynamic-programming algorithm [Felsenstein, Evolutionary trees from DNA sequences: a maximum likelihood approach. J. Mol. Evol. (1981)17:386-376].

## Notation:

Likelihood of  $v$ 's subtree, given that  $v$  has the label  $x$  at position  $j$ :

$$C_j(x, v) = P(\text{ subtree whose root is } v \mid v_j = x)$$

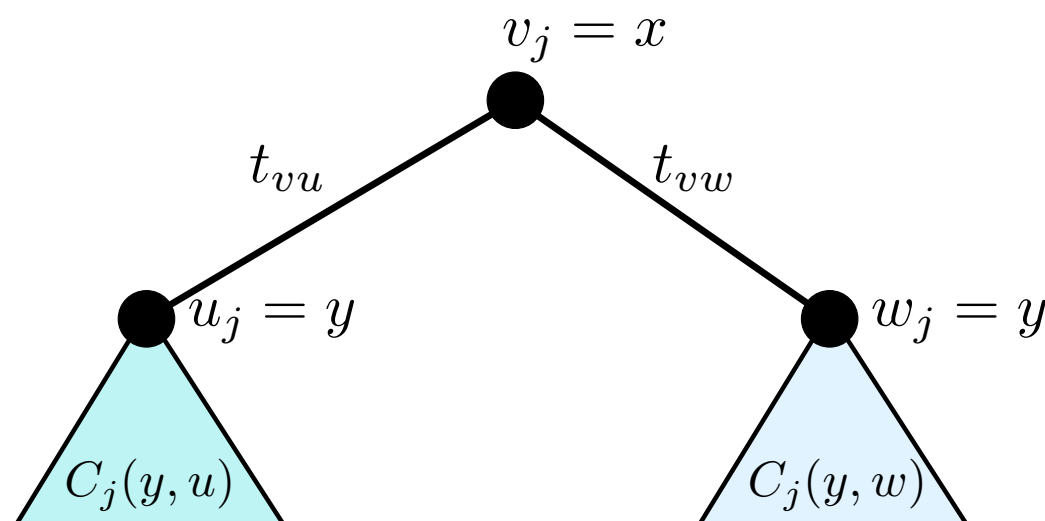


**Initialization:** For each leaf  $v$  and label  $x$ :

$$C_j(x, v) = \begin{cases} 1 & \text{if } v_j = x \\ 0 & \text{otherwise} \end{cases}$$

**Recursion:** Traverse the tree in postorder. For an internal node  $v$  with children  $u$  and  $w$ , compute for each possible label  $x$ :

$$C_j(x, v) = \left[ \sum_y C_j(y, u) \cdot P_{x \rightarrow y}(t_{vu}) \right] \cdot \left[ \sum_y C_j(y, w) \cdot P_{x \rightarrow y}(t_{vw}) \right].$$



**Final solution:**  $L = \prod_{j=1}^m \left[ \sum_x C_j(x, \text{root}) \cdot P(x) \right].$

# Maximizing the Likelihood

- **Optimal Branch Lengths.** Given the topology, find the optimal branch length (optimality = maximum likelihood).

No analytical solution known. Use numerical methods such as conjugate gradients, based on the derivatives  $\frac{\partial}{\partial t_{vw}} P_{x \rightarrow y}(t_{vw})$ .

- **Optimal topology.** Even harder problem.

EM-like methods have been proposed:

Iteratively optimize topology and branch lengths, e.g. “Structural EM” [Friedman et al, J Comput Biol. 2002; 9(2):331-353].

# Bayesian approaches

- Instead of solving for the maximum likelihood tree, investigate the **distribution of trees, given the observations**:  
     $\rightsquigarrow$  **Posterior distribution of trees.**

$M$ : observed characters.  $T$ : topology.  $t$ : edge lengths.

$$\underbrace{P(T, t|M)}_{\text{posterior}} = \frac{\overbrace{P(M|T, t)}^{\text{likelihood}}}{P(M)} \cdot \underbrace{P(T, t)}_{\text{prior}}.$$

- Typically, we do not have the posterior in analytic form, but we might be able to **draw samples from the posterior**.
- Law of large numbers: Frequency of a **property in the sample** will converge to the posterior probability.
- Example: If a particular tree topology is present in some fraction  $r$  of the samples, then  $r$  is an estimate of the posterior probability of this topology.

# The Metropolis Method

- A method for drawing samples from a posterior distribution.
- Proposal mechanism: A procedure  $f$  that generates a tree  $(\tilde{T}, \tilde{t})$  randomly based on the current tree  $(T, t)$  by sampling from a **proposal distribution**.
- Define posteriors  $P_1 = P(T, t|M)$  and  $P_2 = P(\tilde{T}, \tilde{t}|M)$ .
- Step 1: Build a random tree  $(T, t)$  and calculate  $P_1$ .
- Step 2: Build a new  $f(T, t) = (\tilde{T}, \tilde{t})$  and calculate  $P_2$ .
- Step 3: Accept new tree if  $P_2 > P_1$ .  
If  $P_2 < P_1$ , accept only with probability  $P_2/P_1$ .  
If accepted, new sample is  $(\tilde{T}, \tilde{t})$ , otherwise sample is  $(T, t)$ .
- Step 4: If an appropriate number of samples have been taken, stop. Else, go to Step 2.

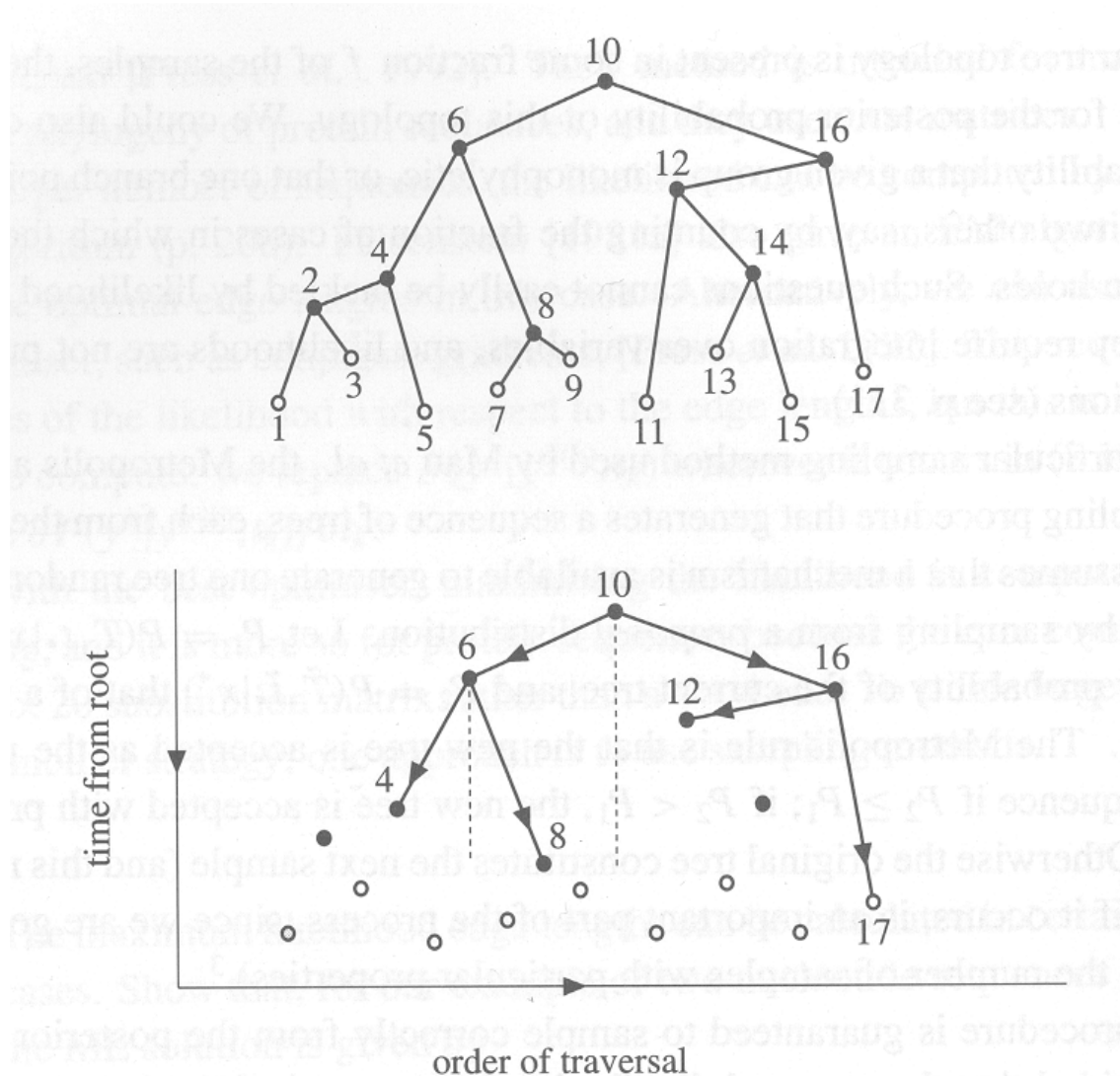
# The Metropolis Method (cont'd)

- Note: only the rate  $P_2/P_1$  must be calculated  
     $\rightsquigarrow$  exponentially large sum  $P(M) = \sum_{\text{all trees } (T,t)} P(M, T, t)$   
in Bayes formula is avoided!
- Guaranteed to **asymptotically sample correctly from the posterior distribution**, if the proposal distribution is symmetric:  
Proposing  $(\tilde{T}, \tilde{t})$  from  $(T, t)$  is the same as proposing  $(T, t)$  from  $(\tilde{T}, \tilde{t})$ .
- Crucial point: find suitable proposal distribution for trees.  
Exploration-exploitation trade-off:
  - If proposed tree is merely sampled randomly, the posterior probabilities will be low  $\rightarrow$  low acceptance rate.
  - If proposed tree is too close to the current tree, many steps will be needed to explore the space of trees.

# A Proposal Distribution for Trees

- (Mau et al., 1996): **Traversal profile.** Equivalent to the original tree (so tree can be reconstructed from profile), but allowing more convenient manipulations of the topology.
- Node is placed at height  $h$  = sum of the edge lengths from root to that node.
- Nodes are regularly spaced horizontally, in the order given by an in-order traversal of the tree.
- For a node  $k$ , all left children have numbers  $< k$ , and all right children  $> k$ .
- Proposal procedure: Randomly shifting the positions of nodes up and down.
- Relative heights of nodes switched  $\rightsquigarrow$  new topology produced.
- Additional proposal mechanism reorders the leaves.

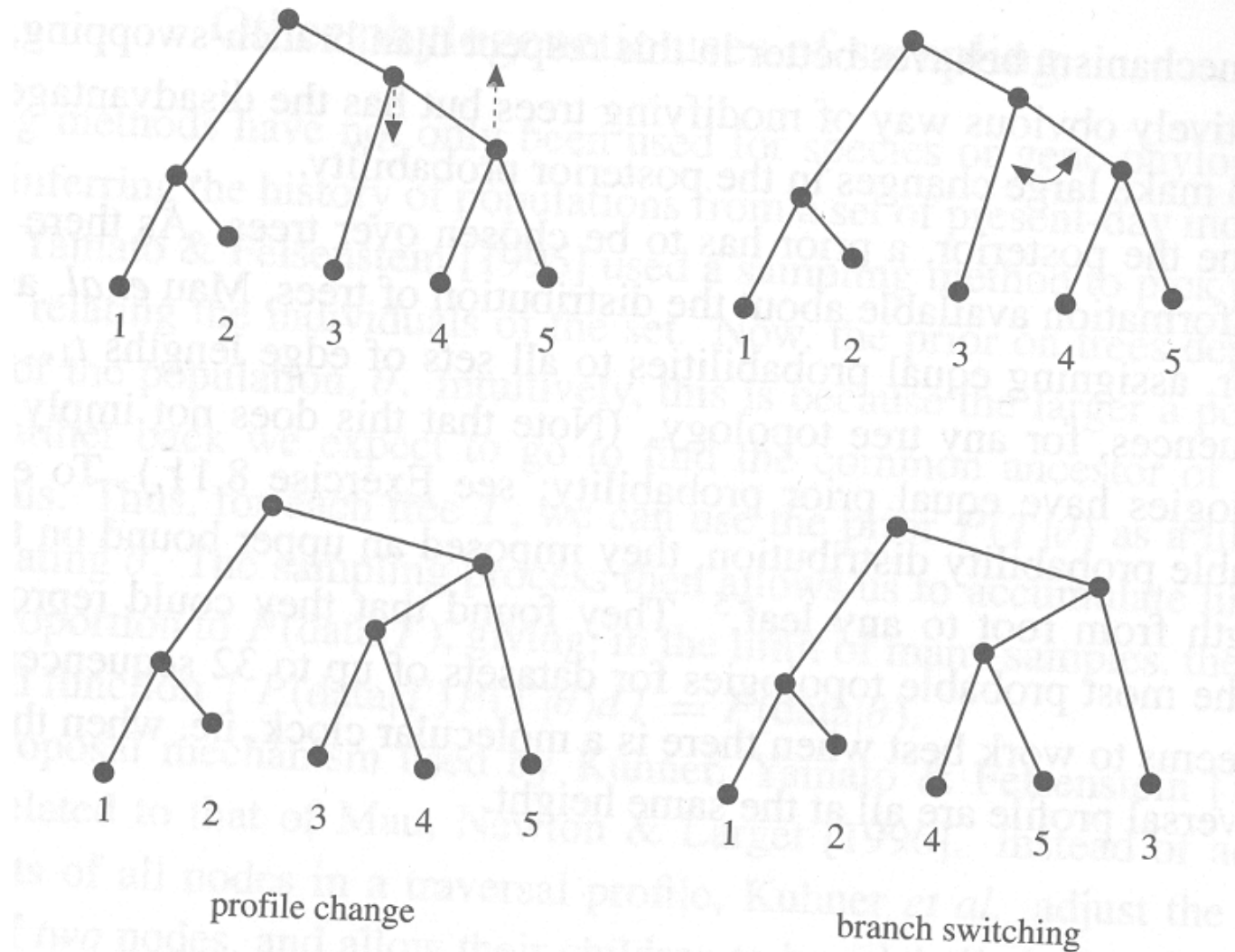
# A Proposal Distribution for Trees



Above: an example of a tree with its nodes numbered in the order of the traversal profile. Below: Reconstruction of the tree from the traversal profile.

Durbin et al., Cambridge University Press. <https://doi.org/10.1017/CBO9780511790492.004>

# A Proposal Distribution for Trees (cont'd)



Durbin et al., Cambridge University Press. <https://doi.org/10.1017/CBO9780511790492.004>