

Error analysis for physics informed neural networks

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4 October 2021

- Neural networks & physics informed neural networks (PINNs)
- Neural network approximation in Sobolev norms
- Error analysis case studies
 - PINNs for the Navier-Stokes equation
 - PINNs for linear Kolmogorov PDEs
- Physics informed operator learning

Joint work with

- S. Lanthaler (ETH Zürich),
- S. Mishra (ETH Zürich),
- A.D. Jagtap (Brown University).

Neural networks

A **feedforward (artificial) neural network** of depth L is a map of the form

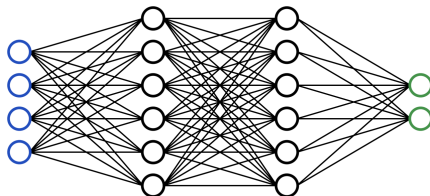
$$\Phi : \mathbb{R}^{n_0} \rightarrow \mathbb{R}^{n_L} : x \mapsto (\mathcal{A}^L \circ \rho^{L-1} \circ \dots \circ \rho^1 \circ \mathcal{A}^1)(x)$$

where

- $\mathcal{A}^\ell : \mathbb{R}^{n_{\ell-1}} \rightarrow \mathbb{R}^{n_\ell}$ are affine linear maps,

$$\mathcal{A}^\ell(x) = W^\ell x + b^\ell \text{ with weights } W^\ell \text{ and bias } b^\ell,$$

- ρ^ℓ are activation functions.



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A feedforward NN is called a **tanh NN** when

- $\tanh : \mathbb{R} \rightarrow \mathbb{R} : x \mapsto \frac{e^x - e^{-x}}{e^x + e^{-x}},$
- $\rho^\ell(x) = (\tanh(x_1), \dots, \tanh(x_{n_\ell}))$ for $\ell = 1, 2, \dots, L-1,$

Network has depth L , width $\max_\ell n_\ell$ and $\sum_\ell n_\ell$ neurons

Neural network approximation theory

Central question

Given function class $\mathcal{F}$ and $f \in \mathcal{F}$, what size should a neural network $\hat{f}$ have such that $\|f - \hat{f}\|_{\mathcal{F}} < \epsilon$?

Typical result (e.g. [Yarotsky, 2017]):

Theorem

For every $\epsilon > 0$ and every $f \in W^{n,\infty}([0,1]^d)$, there exists a tanh neural network $\hat{f}$ with $O(\epsilon^{-d/n})$ neurons such that $\|f - \hat{f}\|_{\infty} < \epsilon$.

NN structure allows for constructive proofs

Sum or composition of NN is a NN

For $\text{ReLU}(x) = \max\{x, 0\} = (x)_+$:

- $x = (x)_+ - (-x)_+$,
- $\max\{a, b\} = a + (b - a)_+$.

For smooth σ with $\sigma'(0) \neq 0$ and $|x| \leq B$:

$$\forall h > 0 : x = \frac{\sigma(xh) - \sigma(-xh)}{2h\sigma'(0)} + O(B^3h^2)$$

PDE is characterized by:

- domain D ,
- differential operator $\mathcal{D} : X \rightarrow Y$,
- boundary operator $\mathcal{B} : X \rightarrow Z$.

We assume that there exists $u \in X$ with

- $\forall x \in D : (\mathcal{D}u)(x) = 0$,
- $\forall y \in \partial D : (\mathcal{B}u)(y) = 0$.

Goal: approximate u with neural network $\hat{u}$ s.t. $\|u - \hat{u}\|_X$ is small

Finding the neural network $\hat{u}$

Goal: find NN $\hat{u}$ such that $\|u - \hat{u}\|_X$ is small

Supervised learning consists of

- select (grid) points y_i and use PDE solver to approximate $u(y_i)$
- training set $\mathcal{S} = \{(y_1, u(y_1)), \dots, (y_N, u(y_N))\} \subset D \times u(D)$,
- approach: minimize $\frac{1}{N} \sum_{n=1}^N \|u(y_n) - \hat{u}(y_n)\|^2$,
- problem: generating training data can be **expensive**,

Finding the neural network $\hat{u}$

Goal: find NN $\hat{u}$ such that $\|u - \hat{u}\|_X$ is small

Problem: generating training data can be **expensive**

Recall that $\mathcal{D}u = \mathcal{B}u = 0 \Rightarrow$ idea: minimize residuals $\|\mathcal{D}\hat{u}\|_Y + \lambda \|\mathcal{B}\hat{u}\|_Z$

Physics informed (unsupervised) learning consists of

- e.g. [Lagaris et al., 2000; Raissi et al., 2019],
- select (grid) points $x_i \in D$ and $y_i \in \partial D$
- training sets $\mathcal{S}_i = \{x_1, \dots, x_N\} \subset D$ and $\mathcal{S}_b = \{y_1, \dots, y_M\} \subset \partial D$ are free $\rightarrow$ **no data generation necessary**,
- approach: minimize $\frac{1}{N} \sum_{n=1}^N \|\mathcal{D}\hat{u}(x_n)\| + \frac{\lambda}{M} \sum_{m=1}^M \|\mathcal{B}\hat{u}(y_m)\|$.

Physics informed learning

Goal: find NN $\hat{u}$ such that $\|u - \hat{u}\|_X$ is small

$\mathcal{D}u = \mathcal{B}u = 0 \Rightarrow$ idea: minimize PINN residual $\|\mathcal{D}\hat{u}\|_Y + \lambda\|\mathcal{B}\hat{u}\|_Z$

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Questions

- 1 **Existence:** Is there $\hat{u}$ such that $\|\mathcal{D}\hat{u}\|_Y + \lambda\|\mathcal{B}\hat{u}\|_Z$ is small? If yes, what is the size of $\hat{u}$?

Physics informed learning

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- 2 **Stability:** If $\|\mathcal{D}\hat{u}\|_Y + \lambda \|\mathcal{B}\hat{u}\|_Z$ is small, will $\|u - \hat{u}\|_X$ be small as well?

Physics informed learning

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- 3 **Generalization:** Does small training error imply small generalization error?

Neural network approximation in Sobolev norms

Approach 1: approximates well in **Sobolev norm** $\Rightarrow$ small PINN residual

Theorem [DR, Lanthaler, and Mishra, 2021b]

For every $N \in \mathbb{N}$ and every $f \in W^{s,\infty}([0,1]^d)$, there exists a tanh neural network $\hat{f}$ with **2 hidden layers** of width N^d such that for every $0 \leq k < s$ it holds that,

$$\left\| f - \hat{f} \right\|_{W^{k,\infty}} \leq C(\ln(cN))^k N^{-s+k},$$

where $c, C > 0$ are independent of N and **explicitly known**.

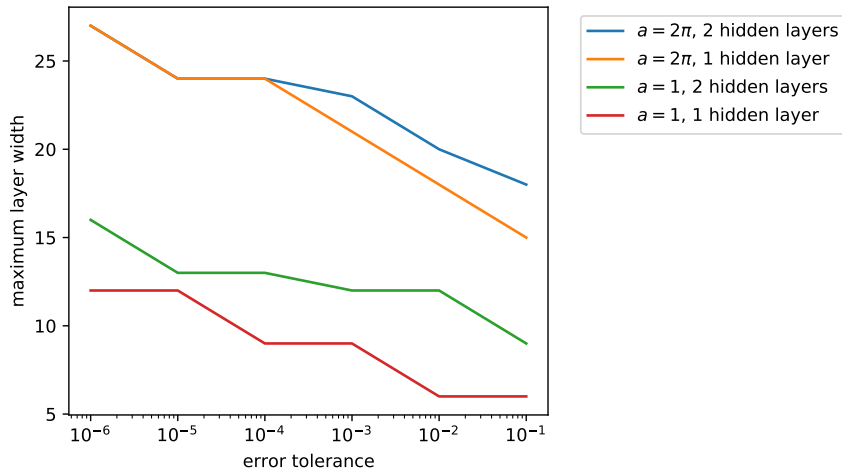
Summary of our work:

- **No unknown parameters**
- **More general norm**
- Faster convergence for analytic functions
- **Fixed depth**

Neural network approximation in Sobolev norms

Layer width of network to approximate

$$f_a : [0, 1] \rightarrow [-1, 1] : x \mapsto \sin(ax), \quad a > 0?$$



PINNs for Navier-Stokes equations

Bounds in $W^{k,\infty}$ -norm $\Rightarrow$ existence of NNs with small PINN error

Case study: Navier-Stokes equations in d space dimensions (periodic BC)

$$\begin{cases} u_t + u \cdot \nabla u + \nabla p - \nu \Delta u = 0 & \text{in } D \times [0, T], \\ \operatorname{div}(u) = 0 & \text{in } D \times [0, T], \\ u(t=0) - u_0 = 0 & \text{in } D. \end{cases} \Rightarrow \text{residuals } \begin{cases} \mathcal{R}_{\text{PDE}} \\ \mathcal{R}_{\text{div}} \\ \mathcal{R}_t \end{cases}$$

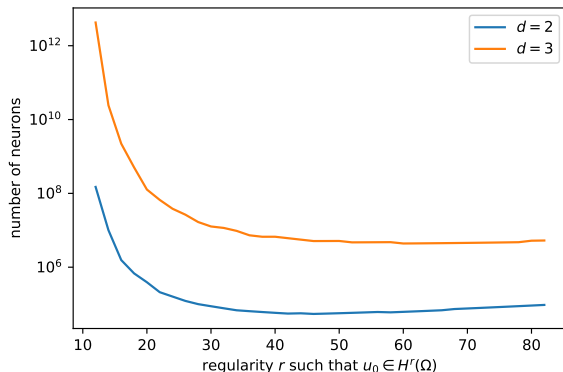
Theorem [DR, Jagtap, and Mishra, 2021a]

Let $u_0 \in H^r$ with $r > \frac{d}{2} + 2k$ and $\operatorname{div}(u_0) = 0$. For every $N \in \mathbb{N}$ there exists a tanh neural network $\hat{u}$ with 2 hidden layers of width N^{d+1} s.t.

$$\|\mathcal{R}_{\text{PDE}}[\hat{u}]\|_{L^2} + \|\mathcal{R}_{\text{div}}[\hat{u}]\|_{L^2} + \|\mathcal{R}_t[\hat{u}]\|_{L^2} \leq C(\ln(cN))^2 N^{-k+2}.$$

PINNs for Navier-Stokes equations

Needed NN size such that PINN error is $< 1\%$ for $u_0 \in H^r(\mathbb{T}^d)$:



$\Rightarrow$ reasonable NN sizes

PINNs for Navier-Stokes equations

So far: existence of NN with small PINN residuals ❶ ✓

Does small PINN loss imply small L^2 -error?

Theorem

$$\|u - \hat{u}\|_{L^2}^2 \leq C(\|\mathcal{R}_{\text{div}}\|_{L^2} + \|\mathcal{R}_{\text{PDE}}\|_{L^2}^2 + \|\mathcal{R}_s\|_{L^2} + \|\mathcal{R}_t\|_{L^2}^2)$$

Yes! Stability ❷ ✓

Does small training error $\mathcal{E}_T(\mathcal{S})$ imply small generalization error?

Theorem

$$\|u - \hat{u}\|_{L^2}^2 \leq C(\mathcal{E}_T(\mathcal{S}) + N_t^{-\frac{2}{d}} + N_{\text{int}}^{-\frac{1}{d+1}} + N_s^{-\frac{1}{d}})$$

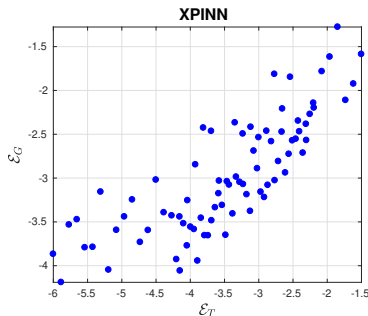
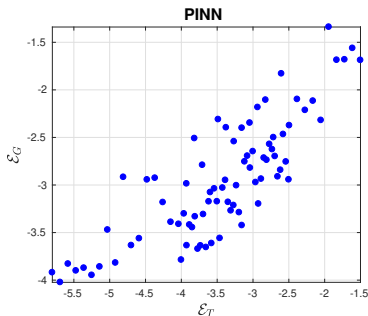
Yes! Generalization ❸ ✓

PINNs for Navier-Stokes

Does small training error $\mathcal{E}_T(S)$ imply small generalization error $\mathcal{E}_G(S)$?

Theorem

$$\mathcal{E}_G^2 = \|u - \hat{u}\|_{L^2}^2 \leq C(\mathcal{E}_T(S) + N_t^{-\frac{2}{d}} + N_{\text{int}}^{-\frac{1}{d+1}} + N_s^{-\frac{1}{d}})$$



So far: Navier-Stokes equations are low-dimensional

Previous estimates suffer from **curse of dimensionality (CoD)**:

- e.g. accuracy $\times 10 \Rightarrow$ size $\times 10^{d/s}$.

Many PDEs are high-dimensional:

- e.g. option pricing: Black-Scholes, Heston ... ,
- experiments show that PINNs can overcome **CoD** [Mishra, Molinaro, Tanios, 2021].

Can we rigourously prove that PINNs overcome the CoD?

PINNs for Kolmogorov PDEs

Focus on linear **Kolmogorov PDEs** with solution u ,

$$\begin{cases} u_t(t,x) = \mathcal{L}[u](t,x) = \frac{1}{2} \text{Trace}(\sigma(x)\sigma(x)^T H_x[u](t,x)) + \mu(x)^T \cdot \nabla_x[u](t,x), \\ u(0,x) = \varphi(x), \\ u(t,y) = \psi(t,y), \quad \forall x \in D, y \in \partial D, t \in [0, T], \end{cases}$$

where $\sigma : \mathbb{R}^d \rightarrow \mathbb{R}^{d \times d}$ and $\mu : \mathbb{R}^d \rightarrow \mathbb{R}^d$ are affine functions.

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Examples

- Heat equation: $\mu = 0$ and $\sigma = \sqrt{\kappa} I_d$
- Black-Scholes equation: μ and σ linear

Goal: ❶ existence, ❷ stability, ❸ generalization

Connection between Kolmogorov PDE and Itô diffusion SDE,

$$dX_t^x = \mu(X_t^x)dt + \sigma(X_t^x)dB_t, \quad X_0^x = x, \quad x \in D, t \in [0, T],$$

with **generator** $(\mathcal{F}\varphi)(X_t^x) = \sum_{i=1}^d \mu_i(X_t^x)(\partial_i \varphi)(X_t^x) + \frac{1}{2} \sum_{i,j,k=1}^d \sigma_{ik}(X_t^x)\sigma_{kj}(X_t^x)(\partial_{ij}^2 \varphi)(X_t^x)$.

Dynkin's formula

If $\varphi \in C^2(\mathbb{R}^d)$ with bounded first partial derivatives, then it holds that

$$(\partial_t u)(x, t) = \mathcal{L}[u](x, t)$$

where u is defined as

$$u(x, t) = \varphi(x) + \mathbb{E} \left[\int_0^t (\mathcal{F}\varphi)(X_\tau^x) d\tau \right] \quad \text{for } x \in D, t \in [0, T].$$

Approach 2:

Theorem [DR and Mishra, 2021a]

If one can approximate φ without the CoD, then there exist constants $\alpha, \beta > 0$ such that for every $\varepsilon > 0$ and $d \in \mathbb{N}$, there exist a constant $\rho_d > 0$ and a tanh neural network $\Psi_{\varepsilon,d}$ with at most $O((d\rho_d)^\alpha \varepsilon^{-\beta})$ neurons such that

$$\|\partial_t \Psi_{\varepsilon,d} - \mathcal{L}[\Psi_{\varepsilon,d}]\|_{L^2(D_d \times [0,T])} + \|\Psi_{\varepsilon,d} - u_d\|_{L^2(\partial(D_d \times [0,T]))} \leq \varepsilon.$$

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Convergence rate is dimension-independent

CoD is fully overcome if $\rho_d = O(d^\gamma)$,

- e.g. when μ and σ are constant,
- ρ_d depends on time regularity of Itô diffusion corresponding to PDE.

Sketch of the proof: use $u(x, t) = \varphi(x) + \mathbb{E} \left[\int_0^t (\mathcal{F}\varphi)(X_\tau^x) d\tau \right]$ and

- replace $\varphi \rightarrow \widehat{\varphi}$ and $\mathcal{F}\varphi \rightarrow \widehat{\mathcal{F}\varphi}$,
- replace $\mathbb{E}$ by average,
- replace $\int_0^t$ by trapezoidal rule,
- μ and σ are affine $\Rightarrow X_t^x = \sum_{i=1}^d (X_t^{e_i} - X_t^0) x_i + X_t^0$
 $\Rightarrow \mathcal{L}[(\mathcal{F}\varphi)(X_\tau^x)]$ is computable.

Conclusion: existence **1** ✓

PINNs for Kolmogorov PDEs

So far: existence of NN with small PINN residuals ❶ ✓

Does small PINN residual imply small L^2 -error?

Theorem [DR and Mishra, 2021a]

$$\|u - \hat{u}\|_{L^2}^2 \leq C(\|\mathcal{R}_{\text{PDE}}\|_{L^2}^2 + \|\mathcal{R}_s\|_{L^2}^2 + \|\mathcal{R}_t\|_{L^2}^2)$$

Yes! Stability ❷ ✓

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Yes! Stability ❷ ✓

Does small training error $\mathcal{E}_T(S)$ imply small generalization error?

Theorem [DR and Mishra, 2021a]

$$\text{With high probability: } \|u - \hat{u}\|_{L^2}^2 \leq C(\mathcal{E}_T(S) + N_t^{-\frac{1}{2}} + N_{\text{int}}^{-\frac{1}{2}} + N_s^{-\frac{1}{4}}).$$

Yes! Generalization ❸ ✓

One step further ...

Deep operator learning: map between infinite-dimensional spaces

- PDEs: $u(0, x) \mapsto u(T, x)$
- Antiderivative operator: $f \mapsto \int f$
- DeepONet, Fourier Neural Operator (FNO), ...
- Error estimates e.g. [Lanthaler, Mishra, Karniadakis, 2021], [Kovachki, Lanthaler, Mishra, 2021]

Physics informed deep operator learning (March 2021)

- Training set: sample points and functions

Theorem [DR and Mishra, 2021b]

Error estimate for DeepONets/FNO + regularity assumptions
 $\Rightarrow$ Error estimate for physics informed DeepONet/FNO

Summary

Physics informed neural networks

- Surrogate models for PDE solutions
- No training data needed

Theoretical investigation

- Existence
- Stability
- Generalization

Results valid for

- Low-dimensional PDEs
- High-dimensional Kolmogorov PDEs

DR and Siddhartha Mishra. Error analysis for PINNs approximating Kolmogorov PDEs. *SAM report 2021-17*, 2021a.

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DR, Ameya D. Jagtap, and Siddhartha Mishra. Error analysis for PINNs approximating the Navier-Stokes equations. *In preparation*, 2021a.

DR, Samuel Lanthaler, and Siddhartha Mishra. On the approximation of functions by tanh neural networks. *Neural Networks*, 2021b.

Course

‘Deep Learning in Scientific Computing’ at ETHZ (spring semester)

Audience: mathematics and CSE master students